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DTC PROJECT NO. 8-CO-160-UXO-021  
REPORT NO. ATC-8744



**STANDARDIZED**  
**UXO TECHNOLOGY DEMONSTRATION SITE**  
**BLIND GRID SCORING RECORD NO. 134**

**SITE LOCATION:**  
**U.S. ARMY YUMA PROVING GROUND**

**DEMONSTRATOR:**  
**U.S. ARMY CORPS OF ENGINEERS**  
**ENGINEERING RESEARCH AND**  
**DEVELOPMENT CENTER**  
**3909 HALLS FERRY ROAD**  
**VICKSBURG, MS 39180-6199**

**TECHNOLOGY TYPE/PLATFORM:**  
**GEM-3/PUSHCART**

**PREPARED BY:**  
**U.S. ARMY ABERDEEN TEST CENTER**  
**ABERDEEN PROVING GROUND, MD 21005-5059**

**AUGUST 2004**



**Prepared for:**  
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14. ABSTRACT This scoring record documents the efforts of U.S. Army Corps of Engineers, Engineering Research and Development Center (ERDC) to detect and discriminate inert unexploded ordnance (UXO) utilizing the APG Standardized UXO Technology Demonstration Site Blind Grid. The scoring record was coordinated by Larry Overbay and by the Standardized UXO Technology Demonstration Site Scoring Committee. Organizations on the committee include the U.S. Army Corps of Engineers, the Environmental, Security Technology Certification Program, the Strategic Environmental Research and Development Program, the Institute for Defense Analysis, the U.S. Army Environmental Center, and the U.S. Army Aberdeen Test Center.					
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## **SECTION 1. GENERAL INFORMATION**

### **1.1 BACKGROUND**

Technologies under development for the detection and discrimination of unexploded ordnance (UXO) require testing so that their performance can be characterized. To that end, Standardized Test Sites have been developed at Aberdeen Proving Ground (APG), Maryland and U.S. Army Yuma Proving Ground (YPG), Arizona. These test sites provide a diversity of geology, climate, terrain, and weather as well as diversity in ordnance and clutter. Testing at these sites is independently administered and analyzed by the government for the purposes of characterizing technologies, tracking performance with system development, comparing performance of different systems, and comparing performance in different environments.

The Standardized UXO Technology Demonstration Site Program is a multi-agency program spearheaded by the U.S. Army Environmental Center (AEC). The U.S. Army Aberdeen Test Center (ATC) and the U.S. Army Corps of Engineers Engineering Research and Development Center (ERDC) provide programmatic support. The program is being funded and supported by the Environmental Security Technology Certification Program (ESTCP), the Strategic Environmental Research and Development Program (SERDP) and the Army Environmental Quality Technology Program (EQT).

### **1.2 SCORING OBJECTIVES**

The objective in the Standardized UXO Technology Demonstration Site Program is to evaluate the detection and discrimination capabilities of a given technology under various field and soil conditions. Inert munitions and clutter items are positioned in various orientations and depths in the ground.

The evaluation objectives are as follows:

- a. To determine detection and discrimination effectiveness under realistic scenarios that vary targets, geology, clutter, topography, and vegetation.
- b. To determine cost, time, and manpower requirements to operate the technology.
- c. To determine demonstrator's ability to analyze survey data in a timely manner and provide prioritized "Target Lists" with associated confidence levels.
- d. To provide independent site management to enable the collection of high quality, ground-truth, geo-referenced data for post-demonstration analysis.

#### **1.2.1 Scoring Methodology**

- a. The scoring of the demonstrator's performance is conducted in two stages. These two stages are termed the RESPONSE STAGE and DISCRIMINATION STAGE. For both stages, the probability of detection ( $P_d$ ) and the false alarms are reported as receiver-operating

characteristic (ROC) curves. False alarms are divided into those anomalies that correspond to emplaced clutter items, measuring the probability of false positive ( $P_{fp}$ ), and those that do not correspond to any known item, termed background alarms.

b. The RESPONSE STAGE scoring evaluates the ability of the system to detect emplaced targets without regard to ability to discriminate ordnance from other anomalies. For the blind grid RESPONSE STAGE, the demonstrator provides the scoring committee with a target response from each and every grid square along with a noise level below which target responses are deemed insufficient to warrant further investigation. This list is generated with minimal processing and, since a value is provided for every grid square, will include signals both above and below the system noise level.

c. The DISCRIMINATION STAGE evaluates the demonstrator's ability to correctly identify ordnance as such and to reject clutter. For the blind grid DISCRIMINATION STAGE, the demonstrator provides the scoring committee with the output of the algorithms applied in the discrimination-stage processing for each grid square. The values in this list are prioritized based on the demonstrator's determination that a grid square is likely to contain ordnance. Thus, higher output values are indicative of higher confidence that an ordnance item is present at the specified location. For digital signal processing, priority ranking is based on algorithm output. For other discrimination approaches, priority ranking is based on human (subjective) judgment. The demonstrator also specifies the threshold in the prioritized ranking that provides optimum performance, (i.e. that is expected to retain all detected ordnance and rejects the maximum amount of clutter).

d. The demonstrator is also scored on EFFICIENCY and REJECTION RATIO, which measures the effectiveness of the discrimination stage processing. The goal of discrimination is to retain the greatest number of ordnance detections from the anomaly list, while rejecting the maximum number of anomalies arising from non-ordnance items. EFFICIENCY measures the fraction of detected ordnance retained after discrimination, while the REJECTION RATIO measures the fraction of false alarms rejected. Both measures are defined relative to performance at the demonstrator-supplied level below which all responses are considered noise, i.e., the maximum ordnance detectable by the sensor and its accompanying false positive rate or background alarm rate.

e. All scoring factors are generated utilizing the Standardized UXO Probability and Plot Program, version 3.1.1.

### **1.2.2 Scoring Factors**

Factors to be measured and evaluated as part of this demonstration include:

a. Response Stage ROC curves:

- (1) Probability of Detection ( $P_d^{res}$ ).
- (2) Probability of False Positive ( $P_{fp}^{res}$ ).
- (3) Background Alarm Rate ( $BAR^{res}$ ) or Probability of Background Alarm ( $P_{BA}^{res}$ ).

b. Discrimination Stage ROC curves:

- (1) Probability of Detection ( $P_d^{\text{disc}}$ ).
- (2) Probability of False Positive ( $P_{fp}^{\text{disc}}$ ).
- (3) Background Alarm Rate ( $\text{BAR}^{\text{disc}}$ ) or Probability of Background Alarm ( $P_{BA}^{\text{disc}}$ ).

c. Metrics:

- (1) Efficiency (E).
- (2) False Positive Rejection Rate ( $R_{fp}$ ).
- (3) Background Alarm Rejection Rate ( $R_{BA}$ ).

d. Other:

- (1) Probability of Detection by Size and Depth.
- (2) Classification by type (i.e., 20-mm, 40-mm, 105-mm, etc.).
- (3) Location accuracy.
- (4) Equipment setup, calibration time and corresponding man-hour requirements.
- (5) Survey time and corresponding man-hour requirements.
- (6) Reacquisition/resurvey time and man-hour requirements (if any).
- (7) Downtime due to system malfunctions and maintenance requirements.

### **1.3 STANDARD AND NONSTANDARD INERT ORDNANCE TARGETS**

The standard and nonstandard ordnance items emplaced in the test areas are listed in Table 1. Standardized targets are members of a set of specific ordnance items that have identical properties to all other items in the set (caliber, configuration, size, weight, aspect ratio, material, filler, magnetic remanence, and nomenclature). Nonstandard targets are ordnance items having properties that differ from those in the set of standardized targets.



**TABLE 1. INERT ORDNANCE TARGETS**

<b>Standard Type</b>	<b>Nonstandard (NS)</b>
20-mm Projectile M55	20-mm Projectile M55
	20-mm Projectile M97
40-mm Grenades M385	40-mm Grenades M385
40-mm Projectile MKII Bodies	40-mm Projectile M813
BDU-28 Submunition	
BLU-26 Submunition	
M42 Submunition	
57-mm Projectile APC M86	
60-mm Mortar M49A3	60-mm Mortar (JPG)
	60-mm Mortar M49
2.75-inch Rocket M230	2.75-inch Rocket M230
	2.75-inch Rocket XM229
MK 118 ROCKEYE	
81-mm Mortar M374	81-mm Mortar (JPG)
	81-mm Mortar M374
105-mm Heat Rounds M456	
105-mm Projectile M60	105-mm Projectile M60
155-mm Projectile M483A1	155-mm Projectile M483A
	500-lb Bomb
	M75 Submunition

JPG = Jefferson Proving Ground.

## **SECTION 2. DEMONSTRATION**

### **2.1 DEMONSTRATOR INFORMATION**

#### **2.1.1 Demonstrator Point of Contact (POC) and Address**

POC: Mr. Jose Llopis  
(601) 634-3164

Address: U.S. Army Corps of Engineers Engineering Research and Development  
Center  
3909 Halls Ferry Road  
Vicksburg, MS 39180-6199

#### **2.1.2 System Description (provided by demonstrator)**

The GEM-3 system is able to collect multiple channels of complex frequency domain electromagnetic interference (EMI) data over a wide range of audio frequencies (30°Hz to 48°kHz). The system is a wheeled pushcart with a 96-cm sensor head, a mounted electronics console, a user interface, and a real-time kinematic (RTK) Global Positioning System (GPS) (fig. 1). The sensor head consists of three coils. The primary transmitter coil is the outer coil in the sensor head. The receiver coil is the inner coil in the sensor head. The bucking transmitter coil is the middle coil in the sensor head. The current in the bucking coil flows in the opposite direction of the current in the primary transmitter coil. This suppresses the dipole moment on the receiver coil that is directly from the primary transmitter coil. The electronics console contains the multifrequency current waveform generator, the analog-to-digital converter receiver electronics, the digital signal processor, and the power management module. The user interface utilizes a personal digital assistant (PDA). The PDA is used for data logging and allows for real-time control of the system. The PDA also allows for real-time display of the data collected. The RTK GPS will require a base station to be set up at a suitable reference point for radio communication with the mobile unit on the GEM-3 system. The GEM-3 system's acquisition of multifrequency data allows for performing what Geophex Ltd., the developer of the system, calls electromagnetic induction spectroscopy (EMIS) on buried objects. EMIS provides a method to discriminate UXO targets from natural and man-made clutter objects by means of their unique, complex (in-phase and quadrature) frequency responses.



Figure 1. Demonstrator's system, GEM-3 pushcart.

### **2.1.3 Data Processing Description (provided by demonstrator)**

The GEM-3 data acquired at the test site will be processed using a combination of ERDC-developed programs and Geosoft's Oasis Montaj. First, basic data corrections such as background subtraction and time-synchronization between the sensor data and GPS data will be performed. The raw data, after these basic corrections, will be submitted in Geosoft XYZ format. Two Response Stage submissions will be made within 30 days. One will be based on a threshold applied to the total magnitude of the sensor inphase and quadrature response for all frequencies. The second will be based on interactive histogram analysis of the data. Data from each of these detection schemes will be used by the target discrimination algorithm to generate separate Discrimination Stage submissions. The discrimination algorithm compares sensor data collected near each detected anomaly with calibration data acquired over the target types of interest at the beginning of the data collection.

One of ERDC's primary objectives for this data acquisition is to obtain high quality data to further our modeling and analysis research. Therefore, ERDC plans to make further data submissions using other detection and discrimination algorithms on this same dataset, alone and in combination with data from other sensors.

#### **2.1.4 Data Submission Format**

Data were submitted for scoring in accordance with data submission protocols outlined in the Standardized UXO Technology Demonstration Site Handbook. These submitted data are not included in this report in order to protect ground truth information.

#### **2.1.5 Demonstrator Quality Assurance (QA) and Quality Control (QC) (provided by demonstrator)**

The operators will perform three levels of quality control (QC) checks: the first day of the project, the beginning of the day, and whenever there is an equipment change (i.e. batteries, data dump, etc.). On the first day of the project, the operators will lay out a 10-meter long line oriented North to South with a ferrite bar at the center. This line will be well marked and used each time we test the instrument and positioning are tested. The operators will test for instrument response over the ferrite bar, as well as conduct a position check and a latency check. The operators will walk the line slowly in two directions and then back the pushcart up until it is centered on the ferrite bar. This will set the location of the ferrite bar as well as the instrument response, which will be referenced every time the operators check the equipment.

Each morning the operators will perform functional equipment checks. The operators will visually inspect all equipment for damage. They will then power up the equipment. The operators will perform static and instrument response tests to ensure that the data is stable when the instrument is in a static position over a marked location. These tests will be performed after the instrument has had sufficient time to warm up.

Quality assurance (QA) will be the responsibility of the project lead; he will ensure that test data will be inspected and recorded each day using a known target (e.g. ferrite bar) with the GEM-3 sensors, and using a reference position with the RTK GPS. Geo-referenced data sets will be inspected at the end of the day for GEM-3 data quality and navigation integrity (reasonableness criteria).

Data analysis will be performed each day. This analysis will include inspection of the data for inconsistencies (bad data and errors) and to verify RTK GPS data show good coverage and limited dropouts. If the data show the sensor or electronics are not taking acceptable data or the RTK GPS dropouts are too numerous/large for data analysis or good coverage, that section will be flagged for a resurvey.

#### **2.1.6 Additional Records**

The following record(s) by this vendor can be accessed via the PDF files at [www.uxotestsites.org](http://www.uxotestsites.org).

## **2.2 YPG SITE INFORMATION**

### **2.2.1 Location**

YPG is located adjacent to the Colorado River in the Sonoran Desert. The UXO Standardized Test Site is located south of Pole Line Road and east of the Countermine Testing and Training Range. The Open Field range, Calibration Grid, Blind Grid, Mogul area, and Desert Extreme area comprise the 350 by 500-meter general test site area. The open field site is the largest of the test sites and measures approximately 200 by 350 meters. To the east of the open field range are the calibration and blind test grids that measure 30 by 40 meters and 40 by 40 meters, respectively. South of the Open Field is the 135- by 80-meter Mogul area consisting of a sequence of man-made depressions. The Desert Extreme area is located southeast of the open field site and has dimensions of 50 by 100 meters. The Desert Extreme area, covered with desert-type vegetation, is used to test the performance of different sensor platforms in a more severe desert conditions/environment.

### **2.2.2 Soil Type**

Soil samples were collected at the YPG UXO Standardized Test Site by ERDC to characterize the shallow subsurface (< 3 m). Both surface grab samples and continuous soil borings were acquired. The soils were subjected to several laboratory analyses, including sieve/hydrometer, water content, magnetic susceptibility, dielectric permittivity, X-ray diffraction, and visual description.

There are two soil complexes present within the site, Riverbend-Carrizo and Cristobal-Gunsight. The Riverbend-Carrizo complex is comprised of mixed stream alluvium, whereas the Cristobal-Gunsight complex is derived from fan alluvium. The Cristobal-Gunsight complex covers the majority of the site. Most of the soil samples were classified as either a sandy loam or loamy sand, with most samples containing gravel-size particles. All samples had a measured water content less than 7 percent, except for two that contained 11-percent moisture. The majority of soil samples had water content between 1 to 2 percent. Samples containing more than 3 percent were generally deeper than 1 meter.

An X-ray diffraction analysis on four soil samples indicated a basic mineralogy of quartz, calcite, mica, feldspar, magnetite, and some clay. The presence of magnetite imparted a moderate magnetic susceptibility, with volume susceptibilities generally greater than 100 by 10<sup>-5</sup> SI.

For more details concerning the soil properties at the YPG test site, go to [www.uxotestsites.org](http://www.uxotestsites.org) on the web to view the entire soils description report.

### 2.2.3 Test Areas

A description of the test site areas at YPG is included in Table 2.

**TABLE 2. TEST SITE AREAS**

<b>Area</b>	<b>Description</b>
Calibration Grid	Contains the 15 standard ordnance items buried in six positions at various angles and depths to allow demonstrator equipment calibration.
Blind Grid	Contains 400 grid cells in a 0.16-hectare (0.39-acre) site. The center of each grid cell contains ordnance, clutter, or nothing.

### **SECTION 3. FIELD DATA**

#### **3.1 DATE OF FIELD ACTIVITIES (5 through 8 May 2003)**

#### **3.2 AREAS TESTED/NUMBER OF HOURS**

Areas tested and total number of hours operated at each site are summarized in Table 3.

**TABLE 3. AREAS TESTED AND  
NUMBER OF HOURS**

<b>Area</b>	<b>Number of Hours</b>
Calibration Lanes	4.75
Blind Grid	3.92

#### **3.3 TEST CONDITIONS**

##### **3.3.1 Weather Conditions**

A YPG weather station located approximately one mile west of the test site was used to record average temperature and precipitation on a half hour basis for each day of operation. The temperatures listed in Table 4 represent the average temperature during field operations from 0700 to 1700 hours while precipitation data represents a daily total amount of rainfall. Hourly weather logs used to generate this summary are provided in Appendix B.

**TABLE 4. TEMPERATURE/PRECIPITATION DATA SUMMARY**

<b>Date, 2003</b>	<b>Average Temperature, °F</b>	<b>Total Daily Precipitation, in.</b>
5 May	Not Available	0.00
6 May	76.5	0.00
7 May	66.1	0.00
8 May	59.4	0.00

##### **3.3.2 Field Conditions**

The field conditions remained dry throughout the demonstration.

##### **3.3.3 Soil Moisture**

Three soil probes were placed at various locations within the site to capture soil moisture data: Calibration, Mogul, and Desert Extreme areas. Measurements were collected in percent moisture and were taken twice daily (morning and afternoon) from five different soil depths (1 to 6 in., 6 to 12 in., 12 to 24 in., 24 to 36 in., and 36 to 48 in.) from each probe. Soil moisture logs are included in Appendix C.

### **3.4 FIELD ACTIVITIES**

#### **3.4.1 Setup/Mobilization**

These activities included initial mobilization and daily equipment preparation and break down. Initial set up accounted for 6 hours and 15 minutes of demonstration time while surveying the Blind Grid. Overall daily breakdown during this four-day period of the survey took 40 minutes.

#### **3.4.2 Calibration**

A total of 4 hours and 45 minutes was spent in the calibration lanes during the survey of the Blind Grid. Data collection in the calibration lanes accounted for 1 hour and 50 minutes of that time. In addition, 2 hrs and 45 minutes were spent in the Calibration Test Pit during these four days.

#### **3.4.3 Downtime Occasions**

Occasions of downtime are grouped into five categories: equipment/data checks or equipment maintenance, equipment failure and repair, weather, Demonstration Site issues, or breaks/lunch. All downtime is included for the purposes of calculating labor costs (section 5) except for downtime due to Demonstration Site issues. Demonstration Site issues, while noted in the Daily Log, are considered non-chargeable downtime for the purposes of calculating labor costs and are not discussed. Breaks and lunches are not discussed either.

**3.4.3.1 Equipment/data checks, maintenance.** A total of 50 minutes was spent checking/downloading data while surveying the Blind Grid.

**3.4.3.2 Equipment failure or repair.** No equipment failures occurred while surveying the Blind Grid.

**3.4.3.3 Weather.** No weather delays occurred during the survey.

#### **3.4.4 Data Collection**

ERDC spent 2 hours and 25 minutes collecting data in the Blind Grid. This time excludes break/lunches and downtimes described in paragraph 3.4.3.

#### **3.4.5 Demobilization**

The ERDC survey crew went on to conducted a full demonstration of the site. Therefore, demobilization did not occur until 22 May 2003. On that day, it took the crew 36 minutes to break down and pack up their equipment.



### **3.5 PROCESSING TIME**

ERDC submitted the raw data from the demonstration activities on the last day of the demonstration, as required. The scoring submittal data was also provided within the required 30-day timeframe.

### **3.6 DEMONSTRATOR'S FIELD PERSONNEL**

Field Manager:	Jose Llopis
Field Engineer:	Troy Broston, Eric Smith
Quality Assurance:	Don Yule
GPS Support:	Tom Berry

### **3.7 DEMONSTRATOR'S FIELD SURVEYING METHOD**

The Calibration Lanes was surveyed in four direction: NS, SN, EW, and WE. Then, repeated in the SN orientation to check for repeatability. The Blind Grid was surveyed in the exact same method.

### **3.8 SUMMARY OF DAILY LOGS**

Daily logs capture all field activities during this demonstration and are located in Appendix D. Activities pertinent to this specific demonstration are indicated in highlighted text.

## SECTION 4. TECHNICAL PERFORMANCE RESULTS

### 4.1 ROC CURVES USING ALL ORDNANCE CATEGORIES

Figure 2 shows the probability of detection for the response stage ( $P_d^{\text{res}}$ ) and the discrimination stage ( $P_d^{\text{disc}}$ ) versus their respective probability of false positive. Figure 3 shows both probabilities plotted against their respective probability of background alarm. Both figures use horizontal lines to illustrate the performance of the demonstrator at two demonstrator-specified points: at the system noise level for the response stage, representing the point below which targets are not considered detectable, and at the demonstrator's recommended threshold level for the discrimination stage, defining the subset of targets the demonstrator would recommend digging based on discrimination. Note that all points have been rounded to protect the ground truth.

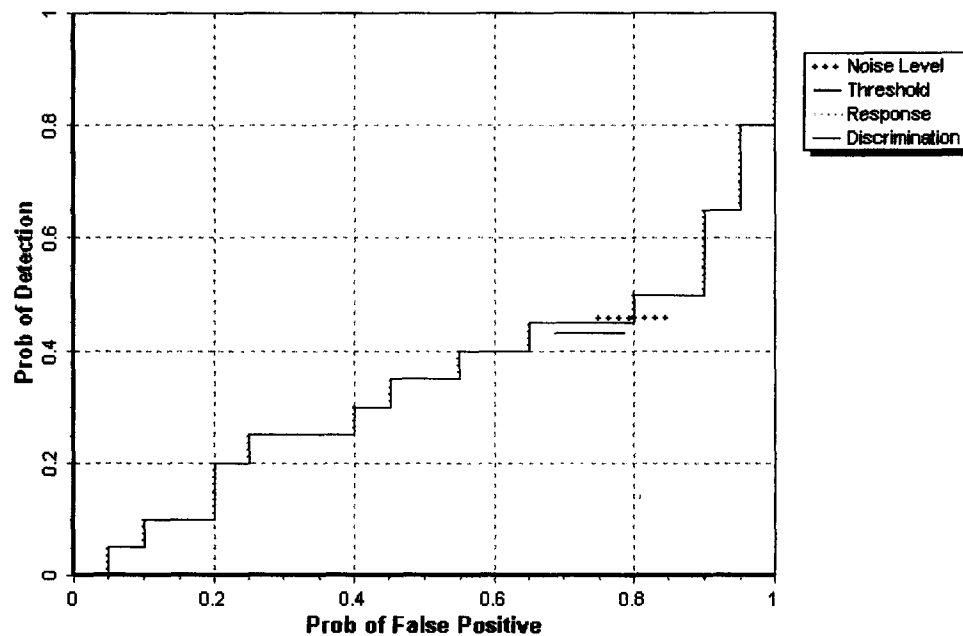


Figure 2. GEM-3 blind grid probability of detection for response and discrimination stages versus their respective probability of false positive over all ordnance categories combined.

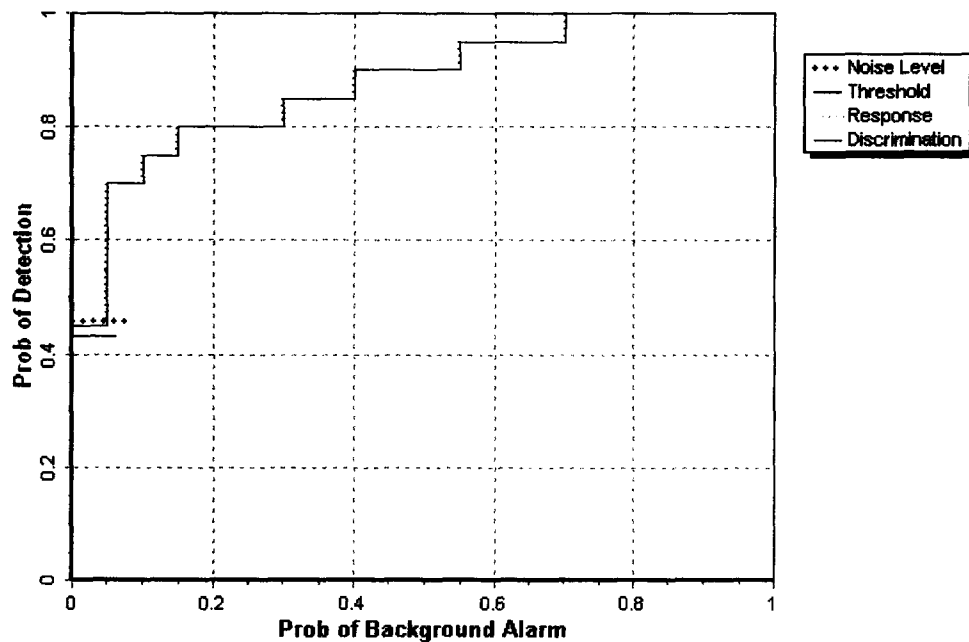


Figure 3. GEM-3 blind grid probability of detection for response and discrimination stages versus their respective probability of background alarm over all ordnance categories combined.

## 4.2 ROC CURVES USING ORDNANCE LARGER THAN 20 MM

Figure 4 shows the probability of detection for the response stage ( $P_d^{res}$ ) and the discrimination stage ( $P_d^{disc}$ ) versus their respective probability of false positive when only targets larger than 20 mm are scored. Figure 5 shows both probabilities plotted against their respective probability of background alarm. Both figures use horizontal lines to illustrate the performance of the demonstrator at two demonstrator-specified points: at the system noise level for the response stage, representing the point below which targets are not considered detectable, and at the demonstrator's recommended threshold level for the discrimination stage, defining the subset of targets the demonstrator would recommend digging based on discrimination. Note that all points have been rounded to protect the ground truth.

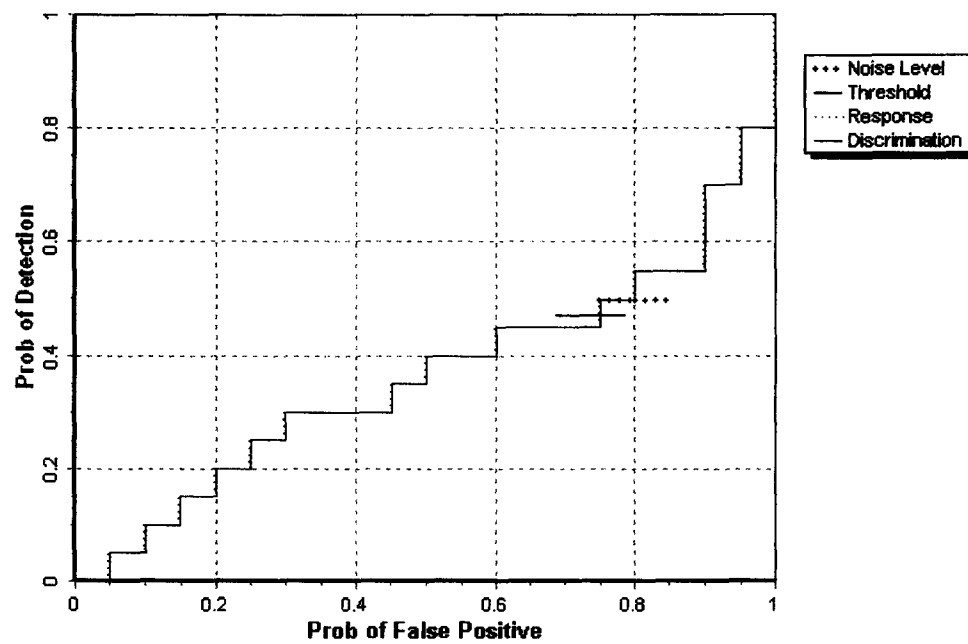


Figure 4. GEM-3 blind grid probability of detection for response and discrimination stages versus their respective probability of false positive for all ordnance larger than 20 mm.

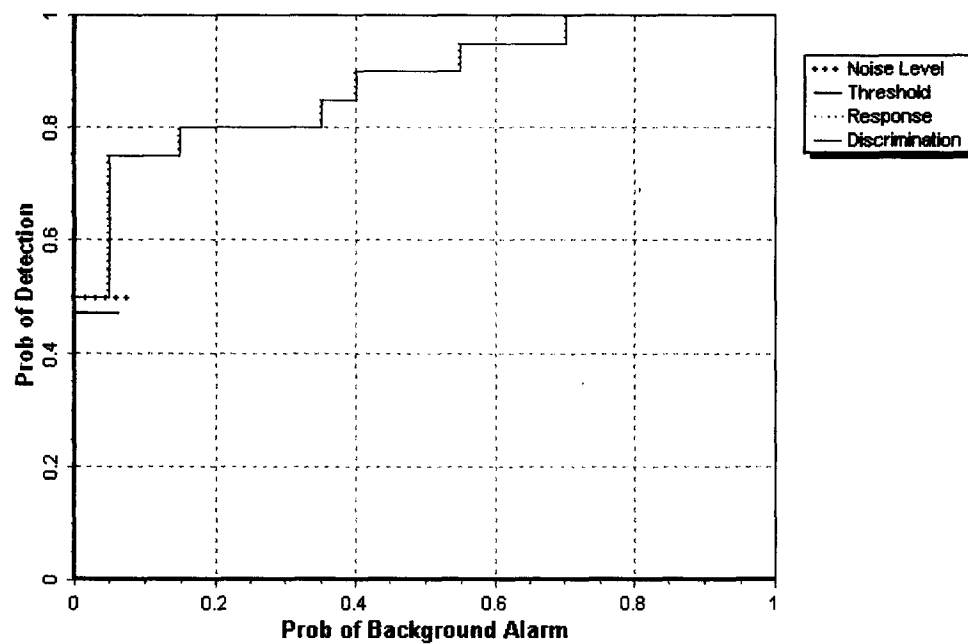


Figure 5. GEM-3 blind grid probability of detection for response and discrimination stages versus their respective probabilities of background alarm for all ordnance larger than 20 mm.

### 4.3 PERFORMANCE SUMMARIES

Results for the Blind Grid test, broken out by size, depth and nonstandard ordnance, are presented in Table 5. (For cost results, see section 5.) Results by size and depth include both standard and nonstandard ordnance. The results by size show how well the demonstrator did at detecting/discriminating ordnance of a certain caliber range. (see app A for size definitions). The results are relative to the number of ordnances emplaced. Depth is measured from the closest point of anomaly to the ground surface.

The RESPONSE STAGE results are derived from the list of anomalies above the demonstrator-provided noise level. The results for the DISCRIMINATION STAGE are derived from the demonstrator's recommended threshold for optimizing UXO field cleanup by minimizing false digs and maximizing ordnance recovery. The lower 90-percent confidence limit on probability of detection and probability of false positive was calculated assuming that the number of detections and false positives are binomially distributed random variables. All results in Table 6 have been rounded to protect the ground truth. However, lower confidence limits were calculated using actual results.

**TABLE 5. SUMMARY OF BLIND GRID RESULTS**

Metric	Overall	Standard	Nonstandard	By Size			By Depth, m		
				Small	Medium	Large	< 0.3	0.3 to <1	>= 1
RESPONSE STAGE									
P <sub>d</sub>	0.45	0.45	0.50	0.30	0.50	0.80	0.50	0.50	0.00
P <sub>d</sub> Low 90% Conf	0.38	0.34	0.35	0.20	0.37	0.58	0.40	0.35	0.00
P <sub>fp</sub>	0.80	-	-	-	-	-	0.85	0.65	0.00
P <sub>fp</sub> Low 90% Conf	0.74	-	-	-	-	-	0.79	0.50	-
P <sub>ba</sub>	0.05	-	-	-	-	-	-	-	-
DISCRIMINATION STAGE									
P <sub>d</sub>	0.45	0.40	0.50	0.25	0.50	0.80	0.45	0.50	0.00
P <sub>d</sub> Low 90% Conf	0.35	0.30	0.35	0.15	0.37	0.58	0.36	0.35	0.00
P <sub>fp</sub>	0.75	-	-	-	-	-	0.80	0.55	0.00
P <sub>fp</sub> Low 90% Conf	0.68	-	-	-	-	-	0.72	0.43	-
P <sub>ba</sub>	0.00	-	-	-	-	-	-	-	-

Response Stage Noise Level: 50

Recommended Discrimination Stage Threshold: 70

Note: The response stage noise level and recommended discrimination stage threshold values are provided by the demonstrator.

#### 4.4 EFFICIENCY, REJECTION RATES, AND TYPE CLASSIFICATION

Efficiency and rejection rates are calculated to quantify the discrimination ability at specific points of interest on the ROC curve: (1) at the point where no decrease in  $P_d$  is suffered (i.e., the efficiency is by definition equal to one) and (2) at the operator selected threshold. These values are reported in Table 6.

**TABLE 6. EFFICIENCY AND REJECTION RATES**

	<b>Efficiency (E)</b>	<b>False Positive Rejection Rate</b>	<b>Background Alarm Rejection Rate</b>
At Operating Point	0.94	0.08	0.50
With No Loss of $P_d$	1.00	0.00	0.17

At the demonstrator's recommended setting, the ordnance items that were detected and correctly discriminated were further scored on whether their correct type could be identified (table 8). Correct type examples include "20-mm projectile, 105-mm HEAT Projectile, and 2.75-inch Rocket". A list of the standard type declaration required for each ordnance item was provided to demonstrators prior to testing. For example, the standard type for the three example items are 20mmP, 105H, and 2.75in, respectively.

**TABLE 7. CORRECT TYPE CLASSIFICATION OF TARGETS CORRECTLY DISCRIMINATED AS UXO**

<b>Size</b>	<b>% Correct</b>
Small	0.0
Medium	0.0
Large	0.0
Overall	0.0

Note: The demonstrator did not attempt to provide type classification.

#### 4.5 LOCATION ACCURACY

The mean location error and standard deviations appear in Table 8. These calculations are based on average missed depth for ordnance correctly identified in the discrimination stage. Depths are measured from the closest point of the ordnance to the surface. For the Blind Grid, only depth errors are calculated, since (X, Y) positions are known to be the centers of each grid square.

**TABLE 8. MEAN LOCATION ERROR AND  
STANDARD DEVIATION (M)**

	<b>Mean</b>	<b>Standard Deviation</b>
Depth	0.00	0.28

## **SECTION 5. ON-SITE LABOR COSTS**

A standardized estimate for labor costs associated with this effort was calculated as follows: the first person at the test site was designated "supervisor", the second person was designated "data analyst", and the third and following personnel were considered "field support". Standardized hourly labor rates were charged by title: supervisor at \$95.00/hour, data analyst at \$57.00/hour, and field support at \$28.50/hour.

Government representatives monitored on-site activity. All on-site activities were grouped into one of ten categories: initial setup/mobilization, daily setup/stop, calibration, collecting data, downtime due to break/lunch, downtime due to equipment failure, downtime due to equipment/data checks or maintenance, downtime due to weather, downtime due to demonstration site issue, or demobilization. See Appendix D for the daily activity log. See section 3.4 for a summary of field activities.

The standardized cost estimate associated with the labor needed to perform the field activities is presented in Table 9. Note that calibration time includes time spent in the Calibration Lanes as well as field calibrations. "Site survey time" includes daily setup/stop time, collecting data, breaks/lunch, downtime due to equipment/data checks or maintenance, downtime due to failure, and downtime due to weather.

**TABLE 9. ON-SITE LABOR COSTS**

	<b>No. People</b>	<b>Hourly Wage</b>	<b>Hours</b>	<b>Cost</b>
<b>Initial Setup</b>				
Supervisor	1	\$95.00	6.25	\$593.75
Data Analyst	1	57.00	6.25	\$356.25
Field Support	3	28.50	6.25	\$534.38
SubTotal				<b>\$1,484.38</b>
<b>Calibration (Including Test Pit)</b>				
Supervisor	1	\$95.00	7.50	\$712.50
Data Analyst	1	57.00	7.50	\$427.50
Field Support	3	28.50	7.50	\$641.25
SubTotal				<b>\$1,781.25</b>
<b>Site Survey</b>				
Supervisor	1	\$95.00	3.75	\$356.25
Data Analyst	1	57.00	3.75	\$213.75
Field Support	3	28.50	3.75	\$320.63
SubTotal				<b>\$890.63</b>

See notes at end of table.



**TABLE 9 (CONT'D)**

	<b>No. People</b>	<b>Hourly Wage</b>	<b>Hours</b>	<b>Cost</b>
<b>Demobilization</b>				
Supervisor	1	\$95.00	0.60	\$57.00
Data Analyst	1	57.00	0.60	\$34.20
Field Support	3	28.50	0.60	\$51.30
Subtotal				<b>\$142.50</b>
Total				<b>\$4,298.76</b>

Notes: Calibration time includes time spent in the Calibration Lanes as well as calibration before each data run.

Site Survey time includes daily setup/stop time, collecting data, breaks/lunch, downtime due to system maintenance, failure, and weather.

**SECTION 6. COMPARISON OF RESULTS TO DATE**

No comparisons to date.

## **SECTION 7. APPENDIXES**

### **APPENDIX A. TERMS AND DEFINITIONS**

#### **GENERAL DEFINITIONS**

**Anomaly:** Location of a system response deemed to warrant further investigation by the demonstrator for consideration as an emplaced ordnance item.

**Detection:** An anomaly location that is within  $R_{\text{halo}}$  of an emplaced ordnance item.

**Emplaced Ordnance:** An ordnance item buried by the government at a specified location in the test site.

**Emplaced Clutter:** A clutter item (i.e., non-ordnance item) buried by the government at a specified location in the test site.

**$R_{\text{halo}}$ :** A pre-determined radius about the periphery of an emplaced item (clutter or ordnance) within which a location identified by the demonstrator as being of interest is considered to be a response from that item. If multiple declarations lie within  $R_{\text{halo}}$  of any item (clutter or ordnance), the declaration with the highest signal output within the  $R_{\text{halo}}$  will be utilized. For the purpose of this program, a circular halo 0.5 meters in radius will be placed around the center of the object for all clutter and ordnance items less than 0.6 meters in length. When ordnance items are longer than 0.6 meters, the halo becomes an ellipse where the minor axis remains 1 meter and the major axis is equal to the length of the ordnance plus 1 meter.

**Small Ordnance:** Caliber of ordnance less than or equal to 40 mm (includes 20-mm projectile, 40-mm projectile, submunitions BLU-26, BLU-63, and M42).

**Medium Ordnance:** Caliber of ordnance greater than 40 mm and less than or equal to 81 mm (includes 57-mm projectile, 60-mm mortar, 2.75 in. Rocket, MK118 Rockeye, 81-mm mortar).

**Large Ordnance:** Caliber of ordnance greater than 81 mm (includes 105-mm HEAT, 105-mm projectile, 155-mm projectile, 500-pound bomb).

**Shallow:** Items buried less than 0.3 meter below ground surface.

**Medium:** Items buried greater than or equal to 0.3 meter and less than 1 meter below ground surface.

**Deep:** Items buried greater than or equal to 1 meter below ground surface.

**Response Stage Noise Level:** The level that represents the point below which anomalies are not considered detectable. Demonstrators are required to provide the recommended noise level for the Blind Grid test area.

**Discrimination Stage Threshold:** The demonstrator selected threshold level that they believe provides optimum performance of the system by retaining all detectable ordnance and rejecting the maximum amount of clutter. This level defines the subset of anomalies the demonstrator would recommend digging based on discrimination.

**Binomially Distributed Random Variable:** A random variable of the type which has only two possible outcomes, say success and failure, is repeated for  $n$  independent trials with the probability  $p$  of success and the probability  $1-p$  of failure being the same for each trial. The number of successes  $x$  observed in the  $n$  trials is an estimate of  $p$  and is considered to be a binomially distributed random variable.

## RESPONSE AND DISCRIMINATION STAGE DATA

The scoring of the demonstrator's performance is conducted in two stages. These two stages are termed the RESPONSE STAGE and DISCRIMINATION STAGE. For both stages, the probability of detection ( $P_d$ ) and the false alarms are reported as receiver operating characteristic (ROC) curves. False alarms are divided into those anomalies that correspond to emplaced clutter items, measuring the probability of false positive ( $P_{fp}$ ) and those that do not correspond to any known item, termed background alarms.

The RESPONSE STAGE scoring evaluates the ability of the system to detect emplaced targets without regard to ability to discriminate ordnance from other anomalies. For the RESPONSE STAGE, the demonstrator provides the scoring committee with the location and signal strength of all anomalies that the demonstrator has deemed sufficient to warrant further investigation and/or processing as potential emplaced ordnance items. This list is generated with minimal processing (e.g., this list will include all signals above the system noise threshold). As such, it represents the most inclusive list of anomalies.

The DISCRIMINATION STAGE evaluates the demonstrator's ability to correctly identify ordnance as such, and to reject clutter. For the same locations as in the RESPONSE STAGE anomaly list, the DISCRIMINATION STAGE list contains the output of the algorithms applied in the discrimination-stage processing. This list is prioritized based on the demonstrator's determination that an anomaly location is likely to contain ordnance. Thus, higher output values are indicative of higher confidence that an ordnance item is present at the specified location. For electronic signal processing, priority ranking is based on algorithm output. For other systems, priority ranking is based on human judgment. The demonstrator also selects the threshold that the demonstrator believes will provide "optimum" system performance, (i.e., that retains all the detected ordnance and rejects the maximum amount of clutter).

**Note:** The two lists provided by the demonstrator contain identical numbers of potential target locations. They differ only in the priority ranking of the declarations.

## RESPONSE STAGE DEFINITIONS

Response Stage Probability of Detection ( $P_d^{\text{res}}$ ):  $P_d^{\text{res}} = (\text{No. of response-stage detections}) / (\text{No. of emplaced ordnance in the test site})$ .

Response Stage False Positive ( $fp^{\text{res}}$ ): An anomaly location that is within  $R_{\text{halo}}$  of an emplaced clutter item.

Response Stage Probability of False Positive ( $P_{fp}^{\text{res}}$ ):  $P_{fp}^{\text{res}} = (\text{No. of response-stage false positives}) / (\text{No. of emplaced clutter items})$ .

Response Stage Background Alarm ( $ba^{\text{res}}$ ): An anomaly in a blind grid cell that contains neither emplaced ordnance nor an emplaced clutter item. An anomaly location in the open field or scenarios that is outside  $R_{\text{halo}}$  of any emplaced ordnance or emplaced clutter item.

Response Stage Probability of Background Alarm ( $P_{ba}^{\text{res}}$ ): Blind Grid only:  $P_{ba}^{\text{res}} = (\text{No. of response-stage background alarms}) / (\text{No. of empty grid locations})$ .

Response Stage Background Alarm Rate ( $BAR^{\text{res}}$ ): Open Field only:  $BAR^{\text{res}} = (\text{No. of response-stage background alarms}) / (\text{arbitrary constant})$ .

Note that the quantities  $P_d^{\text{res}}$ ,  $P_{fp}^{\text{res}}$ ,  $P_{ba}^{\text{res}}$ , and  $BAR^{\text{res}}$  are functions of  $t^{\text{res}}$ , the threshold applied to the response-stage signal strength. These quantities can therefore be written as  $P_d^{\text{res}}(t^{\text{res}})$ ,  $P_{fp}^{\text{res}}(t^{\text{res}})$ ,  $P_{ba}^{\text{res}}(t^{\text{res}})$ , and  $BAR^{\text{res}}(t^{\text{res}})$ .

## DISCRIMINATION STAGE DEFINITIONS

Discrimination: The application of a signal processing algorithm or human judgment to response-stage data that discriminates ordnance from clutter. Discrimination should identify anomalies that the demonstrator has high confidence correspond to ordnance, as well as those that the demonstrator has high confidence correspond to nonordnance or background returns. The former should be ranked with highest priority and the latter with lowest.

Discrimination Stage Probability of Detection ( $P_d^{\text{disc}}$ ):  $P_d^{\text{disc}} = (\text{No. of discrimination-stage detections}) / (\text{No. of emplaced ordnance in the test site})$ .

Discrimination Stage False Positive ( $fp^{\text{disc}}$ ): An anomaly location that is within  $R_{\text{halo}}$  of an emplaced clutter item.

Discrimination Stage Probability of False Positive ( $P_{fp}^{\text{disc}}$ ):  $P_{fp}^{\text{disc}} = (\text{No. of discrimination stage false positives}) / (\text{No. of emplaced clutter items})$ .

Discrimination Stage Background Alarm ( $ba^{\text{disc}}$ ): An anomaly in a blind grid cell that contains neither emplaced ordnance nor an emplaced clutter item. An anomaly location in the open field or scenarios that is outside  $R_{\text{halo}}$  of any emplaced ordnance or emplaced clutter item.

Discrimination Stage Probability of Background Alarm ( $P_{ba}^{disc}$ ):  $P_{ba}^{disc} = (\text{No. of discrimination-stage background alarms})/(\text{No. of empty grid locations})$ .

Discrimination Stage Background Alarm Rate ( $BAR^{disc}$ ):  $BAR^{disc} = (\text{No. of discrimination-stage background alarms})/(\text{arbitrary constant})$ .

Note that the quantities  $P_d^{disc}$ ,  $P_{fp}^{disc}$ ,  $P_{ba}^{disc}$ , and  $BAR^{disc}$  are functions of  $t^{disc}$ , the threshold applied to the discrimination-stage signal strength. These quantities can therefore be written as  $P_d^{disc}(t^{disc})$ ,  $P_{fp}^{disc}(t^{disc})$ ,  $P_{ba}^{disc}(t^{disc})$ , and  $BAR^{disc}(t^{disc})$ .

## RECEIVER-OPERATING CHARACTERISTIC (ROC) CURVES

ROC curves at both the response and discrimination stages can be constructed based on the above definitions. The ROC curves plot the relationship between  $P_d$  versus  $P_{fp}$  and  $P_d$  versus  $BAR$  or  $P_{ba}$  as the threshold applied to the signal strength is varied from its minimum ( $t_{min}$ ) to its maximum ( $t_{max}$ ) value.<sup>1</sup> Figure A-1 shows how  $P_d$  versus  $P_{fp}$  and  $P_d$  versus  $BAR$  are combined into ROC curves. Note that the "res" and "disc" superscripts have been suppressed from all the variables for clarity.

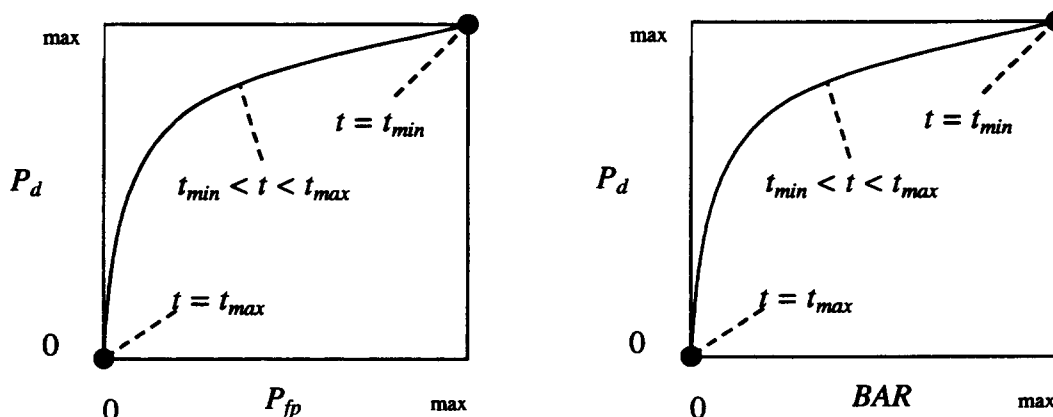


Figure A-1. ROC curves for open field testing. Each curve applies to both the response and discrimination stages.

<sup>1</sup>Strictly speaking, ROC curves plot the  $P_d$  versus  $P_{ba}$  over a pre-determined and fixed number of detection opportunities (some of the opportunities are located over ordnance and others are located over clutter or blank spots). In an open field scenario, each system suppresses its signal strength reports until some bare-minimum signal response is received by the system. Consequently, the open field ROC curves do not have information from low signal-output locations, and, furthermore, different contractors report their signals over a different set of locations on the ground. These ROC curves are thus not true to the strict definition of ROC curves as defined in textbooks on detection theory. Note, however, that the ROC curves obtained in the Blind Grid test sites are true ROC curves.

## METRICS TO CHARACTERIZE THE DISCRIMINATION STAGE

The demonstrator is also scored on efficiency and rejection ratio, which measure the effectiveness of the discrimination stage processing. The goal of discrimination is to retain the greatest number of ordnance detections from the anomaly list, while rejecting the maximum number of anomalies arising from nonordnance items. The efficiency measures the amount of detected ordnance retained by the discrimination, while the rejection ratio measures the fraction of false alarms rejected. Both measures are defined relative to the entire response list, i.e., the maximum ordnance detectable by the sensor and its accompanying false positive rate or background alarm rate.

Efficiency (E):  $E = P_d^{disc}(t^{disc})/P_d^{res}(t_{min}^{res})$ ; Measures (at a threshold of interest), the degree to which the maximum theoretical detection performance of the sensor system (as determined by the response stage  $t_{min}$ ) is preserved after application of discrimination techniques. Efficiency is a number between 0 and 1. An efficiency of 1 implies that all of the ordnance initially detected in the response stage was retained at the specified threshold in the discrimination stage,  $t^{disc}$ .

False Positive Rejection Rate ( $R_{fp}$ ):  $R_{fp} = 1 - [P_{fp}^{disc}(t^{disc})/P_{fp}^{res}(t_{min}^{res})]$ ; Measures (at a threshold of interest), the degree to which the sensor system's false positive performance is improved over the maximum false positive performance (as determined by the response stage  $t_{min}$ ). The rejection rate is a number between 0 and 1. A rejection rate of 1 implies that all emplaced clutter initially detected in the response stage were correctly rejected at the specified threshold in the discrimination stage.

Background Alarm Rejection Rate ( $R_{ba}$ ):

Blind Grid:  $R_{ba} = 1 - [P_{ba}^{disc}(t^{disc})/P_{ba}^{res}(t_{min}^{res})]$ .

Open Field:  $R_{ba} = 1 - [BAR^{disc}(t^{disc})/BAR^{res}(t_{min}^{res})]$ .

Measures the degree to which the discrimination stage correctly rejects background alarms initially detected in the response stage. The rejection rate is a number between 0 and 1. A rejection rate of 1 implies that all background alarms initially detected in the response stage were rejected at the specified threshold in the discrimination stage.

## CHI-SQUARE COMPARISON EXPLANATION:

The Chi-square test for differences in probabilities (or 2 x 2 contingency table) is used to analyze two samples drawn from two different populations to see if both populations have the same or different proportions of elements in a certain category. More specifically, two random samples are drawn, one from each population, to test the null hypothesis that the probability of event A (some specified event) is the same for both populations (ref 3).

A 2 x 2 contingency table is used in the Standardized UXO Technology Demonstration Site Program to determine if there is reason to believe that the proportion of ordnance correctly detected/discriminated by demonstrator X's system is significantly degraded by the more challenging terrain feature introduced. The test statistic of the 2 x 2 contingency table is the

Chi-square distribution with one degree of freedom. Since an association between the more challenging terrain feature and relatively degraded performance is sought, a one-sided test is performed. A significance level of 0.05 is chosen which sets a critical decision limit of 2.71 from the Chi-square distribution with one degree of freedom. It is a critical decision limit because if the test statistic calculated from the data exceeds this value, the two proportions tested will be considered significantly different. If the test statistic calculated from the data is less than this value, the two proportions tested will be considered not significantly different.

An exception must be applied when either a 0 or 100 percent success rate occurs in the sample data. The Chi-square test cannot be used in these instances. Instead, Fischer's test is used and the critical decision limit for one-sided tests is the chosen significance level, which in this case is 0.05. With Fischer's test, if the test statistic is less than the critical value, the proportions are considered to be significantly different.

Standardized UXO Technology Demonstration Site examples, where blind grid results are compared to those from the open field and open field results are compared to those from one of the scenarios, follow. It should be noted that a significant result does not prove a cause and effect relationship exists between the two populations of interest; however, it does serve as a tool to indicate that one data set has experienced a degradation in system performance at a large enough level than can be accounted for merely by chance or random variation. Note also that a result that is not significant indicates that there is not enough evidence to declare that anything more than chance or random variation within the same population is at work between the two data sets being compared.

Demonstrator X achieves the following overall results after surveying each of the three progressively more difficult areas using the same system (results indicate the number of ordnance detected divided by the number of ordnance emplaced):

	Blind Grid	Open Field	Moguls
$P_d^{res}$	100/100 = 1.0	8/10 = .80	20/33 = .61
$P_d^{disc}$	80/100 = 0.80	6/10 = .60	8/33 = .24

$P_d^{res}$ : BLIND GRID versus OPEN FIELD. Using the example data above to compare probabilities of detection in the response stage, all 100 ordnance out of 100 emplaced ordnance items were detected in the blind grid while 8 ordnance out of 10 emplaced were detected in the open field. Fischer's test must be used since a 100 percent success rate occurs in the data. Fischer's test uses the four input values to calculate a test statistic of 0.0075 that is compared against the critical value of 0.05. Since the test statistic is less than the critical value, the smaller response stage detection rate (0.80) is considered to be significantly less at the 0.05 level of significance. While a significant result does not prove a cause and effect relationship exists between the change in survey area and degradation in performance, it does indicate that the detection ability of demonstrator X's system seems to have been degraded in the open field relative to results from the blind grid using the same system.



$P_d^{disc}$ : BLIND GRID versus OPEN FIELD. Using the example data above to compare probabilities of detection in the discrimination stage, 80 out of 100 emplaced ordnance items were correctly discriminated as ordnance in blind grid testing while 6 ordnance out of 10 emplaced were correctly discriminated as such in open field-testing. Those four values are used to calculate a test statistic of 1.12. Since the test statistic is less than the critical value of 2.71, the two discrimination stage detection rates are considered to be not significantly different at the 0.05 level of significance.

$P_d^{res}$ : OPEN FIELD versus MOGULS. Using the example data above to compare probabilities of detection in the response stage, 8 out of 10 and 20 out of 33 are used to calculate a test statistic of 0.56. Since the test statistic is less than the critical value of 2.71, the two response stage detection rates are considered to be not significantly different at the 0.05 level of significance.

$P_d^{disc}$ : OPEN FIELD versus MOGULS. Using the example data above to compare probabilities of detection in the discrimination stage, 6 out of 10 and 8 out of 33 are used to calculate a test statistic of 2.98. Since the test statistic is greater than the critical value of 2.71, the smaller discrimination stage detection rate is considered to be significantly less at the 0.05 level of significance. While a significant result does not prove a cause and effect relationship exists between the change in survey area and degradation in performance, it does indicate that the ability of demonstrator X to correctly discriminate seems to have been degraded by the mogul terrain relative to results from the flat open field using the same system.

## APPENDIX B. DAILY WEATHER LOGS

### TABLE B-1. WEATHER LOG

Weather Data from Yuma Proving Ground				
Date	Time, EDST	Average Temperature, °F	RH, %	Precipitation, in.
5/7/2003	01:00	66.1	33	0.00
5/7/2003	02:00	64.8	35	0.00
5/7/2003	03:00	63.2	36	0.00
5/7/2003	04:00	62.0	37	0.00
5/7/2003	05:00	61.2	37	0.00
5/7/2003	06:00	60.2	38	0.00
5/7/2003	07:00	62.1	37	0.00
5/7/2003	08:00	63.4	38	0.00
5/7/2003	09:00	66.0	36	0.00
5/7/2003	10:00	69.2	33	0.00
5/7/2003	11:00	72.1	30	0.00
5/7/2003	12:00	74.6	26	0.00
5/7/2003	13:00	76.5	25	0.00
5/7/2003	14:00	77.4	24	0.00
5/7/2003	15:00	77.4	23	0.00
5/7/2003	16:00	77.9	23	0.00
5/7/2003	17:00	76.6	25	0.00
5/7/2003	18:00	74.7	26	0.00
5/7/2003	19:00	71.8	33	0.00
5/7/2003	20:00	69.5	36	0.00
5/7/2003	21:00	67.8	40	0.00
5/7/2003	22:00	65.8	45	0.00
5/7/2003	23:00	64.9	46	0.00
5/7/2003	24:00	63.8	47	0.00
5/8/2003	01:00	62.6	47	0.00
5/8/2003	02:00	61.8	45	0.00
5/8/2003	03:00	59.7	45	0.00
5/8/2003	04:00	58.0	48	0.00
5/8/2003	05:00	56.8	53	0.00
5/8/2003	06:00	55.5	56	0.00
5/8/2003	07:00	57.5	53	0.00
5/8/2003	08:00	60.5	47	0.00
5/8/2003	09:00	65.1	40	0.00
5/8/2003	10:00	67.3	36	0.00
5/8/2003	11:00	71.1	30	0.00
5/8/2003	12:00	72.9	29	0.00
5/8/2003	13:00	74.4	27	0.00
5/8/2003	14:00	76.4	24	0.00
5/8/2003	15:00	77.2	23	0.00
5/8/2003	16:00	78.1	22	0.00
5/8/2003	17:00	77.3	24	0.00
5/8/2003	18:00	76.2	22	0.00
5/8/2003	19:00	73.5	22	0.00

**TABLE B-1 (CONT'D)**

<b>Weather Data from Yuma Proving Ground</b>				
<b>Date</b>	<b>Time, EDST</b>	<b>Average Temperature, °F</b>	<b>RH, %</b>	<b>Precipitation, in.</b>
5/8/2003	20:00	69.5	29	0.00
5/8/2003	21:00	67.3	28	0.00
5/8/2003	22:00	64.5	32	0.00
5/8/2003	23:00	62.8	32	0.00
5/8/2003	24:00	60.8	38	0.00
5/9/2003	01:00	58.6	43	0.00
5/9/2003	02:00	57.9	45	0.00
5/9/2003	03:00	56.1	49	0.00
5/9/2003	04:00	54.6	52	0.00
5/9/2003	05:00	55.1	52	0.00
5/9/2003	06:00	55.0	51	0.00
5/9/2003	07:00	56.7	49	0.00
5/9/2003	08:00	59.7	45	0.00
5/9/2003	09:00	62.9	39	0.00
5/9/2003	10:00	65.8	33	0.00
5/9/2003	11:00	67.7	29	0.00
5/9/2003	12:00	69.8	26	0.00
5/9/2003	13:00	71.4	22	0.00
5/9/2003	14:00	72.2	17	0.00
5/9/2003	15:00	73.0	18	0.00
5/9/2003	16:00	75.0	16	0.00
5/9/2003	17:00	76.0	14	0.00
5/9/2003	18:00	75.8	12	0.00
5/9/2003	19:00	73.5	20	0.00
5/9/2003	20:00	71.4	20	0.00
5/9/2003	21:00	68.5	22	0.00
5/9/2003	22:00	66.4	24	0.00
5/9/2003	23:00	65.9	23	0.00
5/9/2003	24:00	63.4	27	0.00
5/10/2003	01:00	60.5	34	0.00
5/10/2003	02:00	59.6	39	0.00
5/10/2003	03:00	56.9	42	0.00
5/10/2003	04:00	54.6	44	0.00
5/10/2003	05:00	53.2	43	0.00
5/10/2003	06:00	51.0	44	0.00
5/10/2003	07:00	58.1	32	0.00
5/10/2003	08:00	64.8	31	0.00
5/10/2003	09:00	68.4	25	0.00
5/10/2003	10:00	72.5	20	0.00
5/10/2003	11:00	76.3	15	0.00
5/10/2003	12:00	77.8	12	0.00
5/10/2003	13:00	79.8	13	0.00
5/10/2003	14:00	81.7	12	0.00
5/10/2003	15:00	81.8	12	0.00
5/10/2003	16:00	83.2	10	0.00

**TABLE B-1 (CONT'D)**

<b>Weather Data from Yuma Proving Ground</b>				
<b>Date</b>	<b>Time, EDST</b>	<b>Average Temperature, °F</b>	<b>RH, %</b>	<b>Precipitation, in.</b>
5/10/2003	17:00	83.3	10	0.00
5/10/2003	18:00	82.7	10	0.00
5/10/2003	19:00	81.6	10	0.00
5/10/2003	20:00	78.1	13	0.00
5/10/2003	21:00	75.4	15	0.00
5/10/2003	22:00	72.8	15	0.00
5/10/2003	23:00	68.9	18	0.00
5/10/2003	24:00	66.1	19	0.00
5/12/2003	01:00	71.2	21	0.00
5/12/2003	02:00	69.7	21	0.00
5/12/2003	03:00	67.2	23	0.00
5/12/2003	04:00	63.2	24	0.00
5/12/2003	05:00	63.4	25	0.00
5/12/2003	06:00	61.7	26	0.00
5/12/2003	07:00	65.9	21	0.00
5/12/2003	08:00	74.7	15	0.00
5/12/2003	09:00	81.7	14	0.00
5/12/2003	10:00	86.5	12	0.00
5/12/2003	11:00	89.3	10	0.00
5/12/2003	12:00	90.8	11	0.00
5/12/2003	13:00	93.0	8	0.00
5/12/2003	14:00	94.3	8	0.00
5/12/2003	15:00	95.7	8	0.00
5/12/2003	16:00	95.0	8	0.00
5/12/2003	17:00	94.7	9	0.00
5/12/2003	18:00	94.7	9	0.00
5/12/2003	19:00	92.2	9	0.00
5/12/2003	20:00	89.5	9	0.00
5/12/2003	21:00	85.3	10	0.00
5/12/2003	22:00	83.4	16	0.00
5/12/2003	23:00	80.4	17	0.00
5/12/2003	24:00	79.1	19	0.00
5/14/2003	01:00	76.0	21	0.00
5/14/2003	02:00	74.1	21	0.00
5/14/2003	03:00	72.4	22	0.00
5/14/2003	04:00	73.2	21	0.00
5/14/2003	05:00	71.8	21	0.00
5/14/2003	06:00	73.4	18	0.00
5/14/2003	07:00	73.2	19	0.00
5/14/2003	08:00	77.0	15	0.00
5/14/2003	09:00	82.6	13	0.00
5/14/2003	10:00	85.0	12	0.00
5/14/2003	11:00	88.9	10	0.00
5/14/2003	12:00	92.4	9	0.00
5/14/2003	13:00	94.8	8	0.00

**TABLE B-1 (CONT'D)**

<b>Weather Data from Yuma Proving Ground</b>				
<b>Date</b>	<b>Time, EDST</b>	<b>Average Temperature, °F</b>	<b>RH, %</b>	<b>Precipitation, in.</b>
5/14/2003	14:00	97.4	7	0.00
5/14/2003	15:00	96.2	6	0.00
5/14/2003	16:00	96.5	7	0.00
5/14/2003	17:00	94.6	9	0.00
5/14/2003	18:00	93.8	7	0.00
5/14/2003	19:00	92.0	8	0.00
5/14/2003	20:00	87.9	10	0.00
5/14/2003	21:00	84.4	11	0.00
5/14/2003	22:00	81.9	11	0.00
5/14/2003	23:00	79.4	12	0.00
5/14/2003	24:00	78.6	12	0.00
5/15/2003	01:00	62.5	39	0.00
5/15/2003	02:00	61.1	40	0.00
5/15/2003	03:00	60.0	44	0.00
5/15/2003	04:00	58.1	49	0.00
5/15/2003	05:00	57.9	51	0.00
5/15/2003	06:00	57.0	52	0.00
5/15/2003	07:00	60.8	46	0.00
5/15/2003	08:00	64.5	45	0.00
5/15/2003	09:00	68.3	37	0.00
5/15/2003	10:00	73.1	31	0.00
5/15/2003	11:00	78.0	26	0.00
5/15/2003	12:00	81.0	23	0.00
5/15/2003	13:00	83.4	22	0.00
5/15/2003	14:00	85.7	20	0.00
5/15/2003	15:00	87.5	18	0.00
5/15/2003	16:00	89.7	17	0.00
5/15/2003	17:00	89.8	17	0.00
5/15/2003	18:00	89.9	17	0.00
5/15/2003	19:00	88.4	18	0.00
5/15/2003	20:00	86.0	19	0.00
5/15/2003	21:00	83.4	21	0.00
5/15/2003	22:00	80.2	22	0.00
5/15/2003	23:00	75.7	25	0.00
5/15/2003	24:00	73.7	26	0.00
5/16/2003	01:00	73.9	29	0.00
5/16/2003	02:00	70.8	32	0.00
5/16/2003	03:00	69.2	32	0.00
5/16/2003	04:00	68.5	33	0.00
5/16/2003	05:00	66.7	35	0.00
5/16/2003	06:00	65.4	35	0.00
5/16/2003	07:00	70.5	30	0.00
5/16/2003	08:00	79.3	23	0.00
5/16/2003	09:00	86.4	17	0.00
5/16/2003	10:00	90.0	14	0.00

**TABLE B-1 (CONT'D)**

<b>Weather Data from Yuma Proving Ground</b>				
<b>Date</b>	<b>Time, EDST</b>	<b>Average Temperature, °F</b>	<b>RH, %</b>	<b>Precipitation, in.</b>
5/16/2003	11:00	92.0	14	0.00
5/16/2003	12:00	94.0	13	0.00
5/16/2003	13:00	95.5	12	0.00
5/16/2003	14:00	97.9	11	0.00
5/16/2003	15:00	98.9	11	0.00
5/16/2003	16:00	99.9	11	0.00
5/16/2003	17:00	99.4	12	0.00
5/16/2003	18:00	99.1	10	0.00
5/16/2003	19:00	97.7	11	0.00
5/16/2003	20:00	93.1	12	0.00
5/16/2003	21:00	87.8	14	0.00
5/16/2003	22:00	86.1	16	0.00
5/16/2003	23:00	83.0	18	0.00
5/16/2003	24:00	80.4	19	0.00
5/19/2003	01:00	79.3	19	0.00
5/19/2003	02:00	77.6	19	0.00
5/19/2003	03:00	75.2	20	0.00
5/19/2003	04:00	73.4	21	0.00
5/19/2003	05:00	71.6	24	0.00
5/19/2003	06:00	68.4	25	0.00
5/19/2003	07:00	74.2	23	0.00
5/19/2003	08:00	80.5	25	0.00
5/19/2003	09:00	84.5	24	0.00
5/19/2003	10:00	89.7	14	0.00
5/19/2003	11:00	94.4	11	0.00
5/19/2003	12:00	97.3	10	0.00
5/19/2003	13:00	99.8	8	0.00
5/19/2003	14:00	101.0	8	0.00
5/19/2003	15:00	101.1	8	0.00
5/19/2003	16:00	101.3	7	0.00
5/19/2003	17:00	101.9	7	0.00
5/19/2003	18:00	101.0	7	0.00
5/19/2003	19:00	99.1	8	0.00
5/19/2003	20:00	95.2	9	0.00
5/19/2003	21:00	91.4	11	0.00
5/19/2003	22:00	88.1	11	0.00
5/19/2003	23:00	83.8	13	0.00
5/19/2003	24:00	81.7	15	0.00
6/4/2003	01:00	81.0	19	0.00
6/4/2003	02:00	80.0	22	0.00
6/4/2003	03:00	78.0	22	0.00
6/4/2003	04:00	75.5	28	0.00
6/4/2003	05:00	75.1	32	0.00
6/4/2003	06:00	74.3	34	0.00
6/4/2003	07:00	77.1	32	0.00

**TABLE B-1 (CONT'D)**

<b>Weather Data from Yuma Proving Ground</b>				
<b>Date</b>	<b>Time, EDST</b>	<b>Average Temperature, °F</b>	<b>RH, %</b>	<b>Precipitation, in.</b>
6/4/2003	08:00	82.1	27	0.00
6/4/2003	09:00	87.3	22	0.00
6/4/2003	10:00	89.9	19	0.00
6/4/2003	11:00	93.9	15	0.00
6/4/2003	12:00	95.8	14	0.00
6/4/2003	13:00	98.5	13	0.00
6/4/2003	14:00	100.8	12	0.00
6/4/2003	15:00	102.5	12	0.00
6/4/2003	16:00	103.5	11	0.00
6/4/2003	17:00	103.4	10	0.00
6/4/2003	18:00	102.5	10	0.00
6/4/2003	19:00	100.0	10	0.00
6/4/2003	20:00	96.6	11	0.00
6/4/2003	21:00	94.1	11	0.00
6/4/2003	22:00	90.9	12	0.00
6/4/2003	23:00	86.7	14	0.00
6/4/2003	24:00	84.1	16	0.00

## APPENDIX C. SOIL MOISTURE

SOIL MOISTURE LOGS (6 through 17, 19 through 22, and 28 through 30 May 2003)

Date	Time	Calibration Area Readings (%)					Time	Mogul Area Readings (%)					Time	Desert Extreme Area Readings (%)				
		0 to 6 in.	6 to 12 in.	12 to 24 in.	24 to 36 in.	36 to 48 in.		0 to 6 in.	6 to 12 in.	12 to 24 in.	24 to 36 in.	36 to 48 in.		0 to 6 in.	6 to 12 in.	12 to 24 in.	24 to 36 in.	36 to 48 in.
5/6/2003	0748	1.8	2.2	3.7	3.6	4.0	0807	1.7	2.0	3.4	4.0	4.1	800	1.7	2.0	3.5	3.9	4.0
	1237	1.8	2.2	3.6	3.6	4.0	1246	1.6	2.0	3.6	3.9	4.0	1254	1.7	2.0	3.4	3.9	4.1
5/7/2003	0723	1.8	2.2	3.6	3.6	3.9	0740	1.6	2.0	3.6	3.9	3.9	733	1.7	2.0	3.4	3.9	4.1
	1255	1.8	2.2	3.7	3.6	4.0	1310	1.6	2.0	3.5	3.9	4.0	1305	1.7	2.0	3.4	3.9	4.1
5/8/2003	0715	1.8	2.2	3.6	3.6	3.9	0724	1.6	2.0	3.6	4.0	3.9	732	1.7	2.0	3.4	3.9	4.1
	1243	1.8	2.2	3.7	3.6	3.9	1250	1.6	2.0	3.5	4.0	4.0	1258	1.7	2.0	3.4	3.9	4.1
5/9/2003	0623	1.8	2.2	3.6	3.6	3.9	0638	1.6	2.0	3.5	3.9	3.9	631	1.7	2.0	3.4	3.9	4.1
	1306	1.8	2.2	3.6	3.6	3.9	1315	1.6	2.0	3.5	3.9	3.9	1324	1.7	2.0	3.4	3.9	4.1
5/10/2003	0618	1.8	2.2	3.7	3.6	3.9	0626	1.6	2.0	3.5	3.9	4.0	634	1.7	2.0	3.4	3.9	4.1
	1203	1.8	2.2	3.6	3.6	3.9	1212	1.6	2.0	3.6	3.9	4.0	1221	1.7	2.0	3.4	3.9	4.1
5/12/2003	0630	1.8	2.2	3.7	3.6	3.9	0638	1.6	2.0	3.6	3.9	4.0	644	1.7	2.0	3.4	3.9	4.1
	1256	1.8	2.2	3.6	3.6	3.9	1305	1.6	2.0	3.5	3.9	4.0	1313	1.7	2.0	3.4	3.9	4.1
5/13/2003	0711	1.8	2.2	3.6	3.6	3.9	0719	1.7	2.0	3.6	3.9	4.0	726	1.7	2.0	3.4	3.9	4.1
	1312	1.8	2.2	3.7	3.6	4.0	1323	1.6	2.0	3.6	3.9	4.0	1332	1.7	2.0	3.4	3.9	4.1
5/14/2003	0630	1.8	2.2	3.7	3.6	4.0	0639	1.7	2.0	3.6	3.9	4.0	647	1.7	2.0	3.4	3.9	4.1
	1302	1.8	2.2	3.7	3.6	3.9	1312	1.7	2.0	3.6	4.0	4.0	1318	1.7	2.0	3.4	3.9	4.1
5/15/2003	0626	1.8	2.2	3.6	3.6	3.9	0640	1.7	2.0	3.6	3.9	4.0	648	1.7	2.0	3.4	3.9	4.1
	1302	1.8	2.2	3.7	3.6	4.0	1310	1.6	2.0	3.6	4.0	4.0	1318	1.7	2.0	3.4	3.9	4.1
5/16/2003	0622	1.8	2.2	3.7	3.6	3.9	0629	1.7	2.0	3.6	4.0	4.0	0637	1.7	2.0	3.4	3.9	4.1
	1250	1.8	2.2	3.6	3.6	3.9	1258	1.6	2.0	3.5	3.9	4.0	1305	1.7	2.0	3.4	3.9	4.1
5/17/2003	0610	1.8	2.2	3.7	3.6	3.9	0618	1.6	2.0	3.6	3.9	4.0	0626	1.7	2.0	3.4	3.9	4.1
	1319	1.8	2.2	3.6	3.6	4.0	1327	1.6	2.0	3.6	3.9	4.0	1334	1.7	2.0	3.4	3.9	4.1
5/19/2003	0600	1.8	2.2	3.6	3.6	4.0	0608	1.6	1.9	3.6	3.9	4.0	0615	1.7	2.0	3.4	4.0	4.1
	1306	1.8	2.2	3.7	3.6	4.0	1316	1.6	2.0	3.6	3.9	4.0	1324	1.7	2.0	3.4	4.0	4.1
5/20/2003	0534	1.8	2.2	3.7	3.6	4.0	0542	1.6	2.0	3.6	3.9	4.0	0550	1.7	2.0	3.4	3.9	4.1
	1311	1.8	2.2	3.7	3.6	4.0	1320	1.6	2.0	3.6	3.9	4.0	1326	1.7	2.0	3.4	4.0	4.1
5/21/2003	0547	1.8	2.2	3.7	3.6	4.0	0555	1.6	2.0	3.6	4.0	4.1	0603	1.7	2.0	3.4	4.0	4.1
	1301	1.8	2.2	3.7	3.6	4.0	1309	1.6	2.0	3.6	4.0	4.0	1316	1.7	2.0	3.4	4.0	4.1
5/22/2003	0535	1.8	2.2	3.7	3.6	4.0	0543	1.6	2.0	3.6	4.0	4.0	0550	1.7	2.0	3.4	4.0	4.1
	1303	1.8	2.2	3.7	3.6	4.0	1311	1.6	2.0	3.6	4.0	4.0	1318	1.7	2.0	3.4	4.0	4.1
5/28/2003	0722	1.8	2.2	3.7	3.6	4.0	0730	1.6	2.0	3.6	4.0	4.0	0743	1.7	2.0	3.4	4.0	4.1
	1210	1.8	2.2	3.7	3.6	4.0	1218	1.6	2.0	3.6	4.0	4.0	1225	1.7	2.0	3.4	4.0	4.1
5/29/2003	0645	1.8	2.2	3.7	3.6	4.0	0653	1.6	2.0	3.6	4.0	4.0	0700	1.7	2.0	3.4	4.0	4.1
	1222	1.8	2.2	3.7	3.6	4.0	1230	1.6	2.0	3.6	4.0	4.0	1237	1.7	2.0	3.4	4.0	4.1
5/30/2003	0600	1.8	2.2	3.7	3.6	4.0	0609	1.6	2.0	3.6	4.0	4.0	0616	1.7	2.0	3.4	4.0	4.1
	1239	1.8	2.2	3.7	3.6	4.0	1248	1.6	2.0	3.6	4.0	4.0	1255	1.7	2.0	3.4	4.0	4.1



# APPENDIX D. DAILY ACTIVITY LOGS

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions
5/5/2003		CALIBRATION LANES	1015	1045	30	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	DRY
5/5/2003	4	CALIBRATION LANES	1045	1100	15	BREAK/LUNCH	LUNCH	NA	NA	NA	DRY
5/5/2003	4	CALIBRATION LANES	1100	1530	270	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	DRY
5/5/2003	4	CALIBRATION LANES	1530	1600	30	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	DRY
5/6/2003	5	CALIBRATION LANES	0730	0815	45	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	GPS	NA	NA	DRY
5/6/2003	5	CALIBRATION LANES	0815	0915	60	COLLECTING DATA	RUNNING CAL LANE, BI DIRECTION, NORTH/SOUTH	NA	NA	NA	DRY
5/6/2003	5	CALIBRATION LANES	0915	1030	75	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	DRY
5/6/2003	5	CALIBRATION LANES	1030	1120	50	COLLECTING DATA	RUNNING CAL LANE BI DIRECTION EAST/WEST	GPS	NA	NA	DRY
5/6/2003	5	CALIBRATION LANES	1120	1140	70	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	NA	NA	NA	DRY
5/6/2003	5	CALIBRATION LANES	1140	1210	30	BREAK/LUNCH	LUNCH	GPS	NA	NA	DRY
5/6/2003	5	CALIBRATION LANES	1210	1240	30	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	NA	NA	NA	DRY
5/6/2003	5	BLIND TEST GRID	1240	1355	75	COLLECTING DATA	RUNNING BTG, BIDIRECTION EAST/WEST	GPS	NA	NA	DRY
5/6/2003	5	BLIND TEST GRID	1355	1430	35	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	DRY
5/6/2003	5	CALIBRATION PIT	1430	1450	20	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	GPS	NA	NA	DRY
5/6/2003	5	CALIBRATION PIT	1450	1515	25	COLLECTING DATA	COLLECT DATA OVER PIT	GPS	NA	NA	DRY

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions
5/6/2003	5	CALIBRATION PIT	1515	1520	5	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHANGE OUT BATTERY	GPS	NA	NA	DRY
5/6/2003	5	CALIBRATION PIT	1520	1525	5	COLLECTING DATA	COLLECT DATA OVER PIT	GPS	NA	NA	DRY
5/6/2003	5	CALIBRATION PIT	1525	1535	10	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	DRY
5/7/2003	4	OPEN RANGE	0715	0855	100	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	DRY
5/7/2003	4	OPEN RANGE	0855	1035	100	COLLECTING DATA	RUNNING OPEN RANGE, GRID A2, BIDIRECTIONAL E/W	GPS	NA	NA	DRY
5/7/2003	4	OPEN RANGE	1035	1115	40	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	DRY
5/7/2003	4	OPEN RANGE	1115	1125	10	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	GPS	NA	NA	DRY
5/7/2003	4	OPEN RANGE	1125	1300	95	COLLECTING DATA	RUNNING OPEN RANGE, GRID A3, BIDIRECTIONAL E/W	GPS	NA	NA	DRY
5/7/2003	4	OPEN RANGE	1300	1330	30	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	DRY
5/7/2003	4	OPEN RANGE	1330	1350	20	BREAK/LUNCH	BREAK	NA	NA	NA	DRY
5/7/2003	4	OPEN RANGE	1350	1400	10	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	DRY
5/7/2003	4	OPEN RANGE	1400	1530	90	COLLECTING DATA	RUNNING OPEN RANGE GRID G2, BIDIRECTIONAL E/W	GPS	NA	NA	DRY
5/7/2003	4	OPEN RANGE	1530	1550	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	DRY
5/7/2003	4	OPEN RANGE	1550	1600	10	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	DRY
5/8/2003	5	OPEN RANGE	0700	0745	45	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	DRY
5/8/2003	5	OPEN RANGE	0745	0950	125	COLLECTING DATA	RUNNING OPEN RANGE, GRID G3 G4, BIDIRECTIONAL E/W	GPS	NA	NA	DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions
5/8/2003	5	OPEN RANGE	0950	1020	30	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	COOL/WINDY DRY
5/8/2003	5	BLIND TEST GRID	1020	1130	70	COLLECTING DATA	RUNNING BTG BIDIRECTIONAL NORTH/ SOUTH	GPS	NA	NA	HOT/WINDY DRY
5/8/2003	5	BLIND TEST GRID	1130	1145	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT/WINDY DRY
5/8/2003	5	BLIND TEST GRID	1145	1215	30	BREAK/LUNCH	LUNCH	GPS	NA	NA	HOT/WINDY DRY
5/8/2003	5	OPEN RANGE	1215	1300	45	SET UP/MOBILIZATION	LAYOUT LANES WITH ROPE	NA	NA	NA	HOT/WINDY DRY
5/8/2003	5	CALIBRATION PIT	1300	1440	100	COLLECTING DATA	COLLECT DATA OVER PIT	GPS	NA	NA	HOT/WINDY DRY
5/8/2003	5	CALIBRATION PIT	1440	1500	20	BREAK/LUNCH	BREAK	NA	NA	NA	HOT/WINDY DRY
5/8/2003	5	OPEN RANGE	1500	1550	50	SET UP/MOBILIZATION	LAYOUT LANES WITH ROPE	NA	NA	NA	HOT/WINDY DRY
5/8/2003	5	OPEN RANGE	1550	1600	10	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT/WINDY DRY
5/9/2003	4	OPEN RANGE	0645	0720	35	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	COOL DRY
5/9/2003	4	OPEN RANGE	0720	0845	85	COLLECTING DATA	RUNNING OPEN RANGE, GRID F2,F3,F4,F5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	COOL/WINDY DRY
5/9/2003	4	OPEN RANGE	0845	0905	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	COOL/WINDY DRY
5/9/2003	4	OPEN RANGE	0905	1030	85	COLLECTING DATA	RUNNING OPEN RANGE, GRID F2,F3,F4,F5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	COOL/WINDY DRY
5/9/2003	4	OPEN RANGE	1030	1100	30	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	COOL/WINDY DRY
5/9/2003	4	OPEN RANGE	1100	1130	30	BREAK/LUNCH	LUNCH	NA	NA	NA	COOL/WINDY DRY

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions
5/9/2003	4	OPEN RANGE	1130	1250	80	COLLECTING DATA	RUNNING OPEN RANGE, GRID F2,F3,F4,F5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT/WINDY DRY
5/9/2003	4	OPEN RANGE	1250	1300	10	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHANGE OUT PROCESSOR UNIT	GPS	NA	NA	HOT/WINDY DRY
5/9/2003	5	OPEN RANGE	1300	1330	30	COLLECTING DATA	RUNNING OPEN RANGE, GRID F2,F3,F4,F5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT/WINDY DRY
5/9/2003	5	OPEN RANGE	1330	1430	60	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT/WINDY DRY
5/9/2003	5	OPEN RANGE	1430	1445	15	COLLECTING DATA	RUNNING OPEN RANGE, GRID F2,F3,F4,F5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT/WINDY DRY
5/9/2003	5	OPEN RANGE	1445	1500	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHANGE OUT BATTERY	GPS	NA	NA	HOT/WINDY DRY
5/9/2003	5	OPEN RANGE	1500	1520	20	COLLECTING DATA	RUNNING OPEN RANGE, GRID F2,F3,F4,F5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT/WINDY DRY
5/9/2003	5	OPEN RANGE	1520	1540	20	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT/WINDY DRY
5/10/2003	5	OPEN RANGE	0630	0700	30	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	COOL DRY
5/10/2003	5	OPEN RANGE	0700	0826	86	COLLECTING DATA	RUNNING OPEN RANGE, GRID E2,E3,E4,E5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	COOL DRY
5/10/2003	5	OPEN RANGE	0826	0828	2	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	SWAPPED OUT FIELD COMPUTER	GPS	NA	LINEAR	COOL DRY
5/10/2003	5	OPEN RANGE	0828	1015	107	COLLECTING DATA	RUNNING OPEN RANGE, GRID E2,E3,E4,E5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT DRY
5/10/2003	5	OPEN RANGE	1015	1040	25	BREAK/LUNCH	LUNCH	NA	NA	NA	HOT DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions
5/10/2003	5	OPEN RANGE	1040	1100	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK COLLECTING DATA	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	DRY
5/10/2003	4	OPEN RANGE	1100	1243	103		RUNNING OPEN RANGE, GRID E2,E3,E4,E5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	DRY
5/10/2003	4	OPEN RANGE	1243	1246	3	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK COLLECTING DATA	CHANGE OUT PROCESSOR UNIT	GPS	NA	NA	DRY
5/10/2003	4	OPEN RANGE	1246	1340	54		RUNNING OPEN RANGE, GRID E2,E3,E4,E5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	DRY
5/10/2003	4	OPEN RANGE	1340	1400	20	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	GPS	NA	NA	DRY
5/12/2003	5	OPEN RANGE	0700	0721	21	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	GPS	NA	NA	DRY
5/12/2003	5	OPEN RANGE	0721	0725	4	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	DRY
5/12/2003	5	OPEN RANGE	0725	0825	60	COLLECTING DATA	RUNNING OPEN RANGE, GRID E2,E3,E4,E5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	DRY
5/12/2003	5	OPEN RANGE	0825	0935	50	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK COLLECTING DATA	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	DRY
5/12/2003	5	OPEN RANGE	0935	1025	50	COLLECTING DATA	RUNNING OPEN RANGE, GRID A4,A5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	DRY
5/12/2003	5	OPEN RANGE	1025	1030	5	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK COLLECTING DATA	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	DRY
5/12/2003	5	OPEN RANGE	1030	1325	175	DOWNTIME DUE TO EQUIPMENT FAILURE SET UP/MOBILIZATION	WHEEL AXLE BROKE	NA	NA	NA	DRY
5/12/2003	5	OPEN RANGE	1325	1330	5		BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions
5/13/2003	4	OPEN RANGE	1130	1215	45	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	GPS	NA	NA	DRY
5/13/2003	4	OPEN RANGE	1215	1300	45	COLLECTING DATA	RUNNING OPEN RANGE, A4,A5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	DRY
5/13/2003	4	OPEN RANGE	1300	1320	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	DRY
5/13/2003	4	OPEN RANGE	1320	1430	70	COLLECTING DATA	RUNNING OPEN RANGE, A4,A5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	DRY
5/13/2003	4	OPEN RANGE	1430	1447	17	BREAK/LUNCH	BREAK	NA	NA	NA	DRY
5/13/2003	4	OPEN RANGE	1447	1535	48	COLLECTING DATA	RUNNING OPEN RANGE, A4,A5 BIDIRECTIONAL E/W	NA	NA	LINEAR	DRY
5/13/2003	4	OPEN RANGE	1535	1545	10	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	DRY
5/13/2003	4	OPEN RANGE	1545	1600	15	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	DRY
5/14/2003	5	OPEN RANGE	0630	0735	65	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	HUMID
5/14/2003	5	OPEN RANGE	0735	0739	4	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	LINEAR	HUMID
5/14/2003	5	OPEN RANGE	0739	0850	71	COLLECTING DATA	RUNNING OPEN RANGE, A4,A5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HUMID
5/14/2003	5	OPEN RANGE	0850	0920	30	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HUMID
5/14/2003	5	OPEN RANGE	0920	1020	60	COLLECTING DATA	RUNNING OPEN RANGE, D4,D5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HUMID
5/14/2003	5	OPEN RANGE	1020	1035	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HUMID
5/14/2003	5	OPEN RANGE	1035	1130	55	BREAK/LUNCH	LUNCH	NA	NA	NA	HUMID

Date	No. of People	Area Tested	Status		Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method-Other Explain	Pattern	Field Conditions	
			Start Time	Stop Time							WARM	HUMID
5/14/2003	5	OPEN RANGE	1130	1325	115	COLLECTING DATA	RUNNING OPEN RANGE, D4,D5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	WARM	HUMID
5/14/2003	5	OPEN RANGE	1325	1400	35	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	WARM	HUMID
5/14/2003	5	OPEN RANGE	1400	1430	30	BREAK/LUNCH	BREAK	NA	NA	NA	WARM	HUMID
5/14/2003	5	OPEN RANGE	1430	1530	120	COLLECTING DATA	RUNNING OPEN RANGE, D4,D5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	WARM	HUMID
5/14/2003	5	OPEN RANGE	1530	1600	30	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	WARM	HUMID
5/15/2003	5	OPEN RANGE	0645	0710	25	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	COOL	DRY
5/15/2003	5	OPEN RANGE	0710	0735	25	COLLECTING DATA	RUNNING OPEN RANGE, B2,B3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	COOL	DRY
5/15/2003	5	OPEN RANGE	0735	0742	7	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	COOL	DRY
5/15/2003	5	OPEN RANGE	0742	0750	8	COLLECTING DATA	RUNNING OPEN RANGE, B2,B3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	COOL	DRY
5/15/2003	5	OPEN RANGE	0750	0755	5	DOWNTIME DUE TO EQUIPMENT FAILURE	GPS DOWN	GPS	NA	NA	COOL	DRY
5/15/2003	5	OPEN RANGE	0755	0925	90	COLLECTING DATA	RUNNING OPEN RANGE, B2,B3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	COOL	DRY
5/15/2003	5	OPEN RANGE	0925	0945	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	COOL	DRY
5/15/2003	5	OPEN RANGE	0945	1140	115	COLLECTING DATA	RUNNING OPEN RANGE, B2,B3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/15/2003	5	OPEN RANGE	1140	1150	10	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/15/2003	5	OPEN RANGE	1150	1250	60	BREAK/LUNCH	CHOW	NA	NA	NA	HOT	DRY

Date	No. of People	Area Tested	Status		Duration, min	Operational Status	Operational Status - Comments	Track		Pattern	Field Conditions	
			Start Time	Stop Time				Method	Method=Other Explain			
5/15/2003	5	OPEN RANGE	1250	1255	5	SET UP/MOBILIZATION	SET UP ON C4,C5	NA	NA	NA	HOT	DRY
5/15/2003	5	OPEN RANGE	1255	1320	25	COLLECTING DATA	RUNNING OPEN RANGE, C4,C5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/15/2003	5	OPEN RANGE	1320	1325	5	DOWNTIME DUE TO EQUIPMENT FAILURE	COMMUNICATION ERROR INFIELD COMPUTER	GPS	NA	NA	HOT	DRY
5/15/2003	5	OPEN RANGE	1325	1330	5	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHANGE OUT FIELD COMPUTERS	GPS	NA	NA	HOT	DRY
5/15/2003	5	OPEN RANGE	1330	1530	120	COLLECTING DATA	RUNNING OPEN RANGE, C4,C5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/15/2003	5	OPEN RANGE	1530	1600	30	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT	DRY
5/16/2003	4	OPEN RANGE	0640	0655	15	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	COOL	DRY
5/16/2003	4	OPEN RANGE	0655	0700	5	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	COOL	DRY
5/16/2003	4	OPEN RANGE	0700	0825	85	COLLECTING DATA	RUNNING OPEN RANGE, C4,C5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	COOL	DRY
5/16/2003	4	OPEN RANGE	0825	0850	25	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	COOL	DRY
5/16/2003	4	OPEN RANGE	0850	0900	10	SET UP/MOBILIZATION	SET UP ON D3	NA	NA	NA	COOL	DRY
5/16/2003	4	OPEN RANGE	0900	1110	130	COLLECTING DATA	RUNNING OPEN RANGE, D3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/16/2003	4	OPEN RANGE	1110	1125	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/16/2003	4	OPEN RANGE	1125	1235	70	BREAK/LUNCH	CHOW	NA	NA	NA	HOT	DRY
5/16/2003	4	OPEN RANGE	1235	1330	55	COLLECTING DATA	RUNNING OPEN RANGE, D3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/16/2003	4	OPEN RANGE	1330	1410	40	BREAK/LUNCH	BREAK	NA	NA	NA	HOT	DRY



Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions
5/16/2003	4	OPEN RANGE	1410	1515	65	COLLECTING DATA	RUNNING OPEN RANGE, D3 BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA	GPS	NA	LINEAR	HOT DRY
5/16/2003	4	OPEN RANGE	1515	1530	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK SET UP/MOBILIZATION		GPS	NA	NA	HOT DRY
5/16/2003	4	OPEN RANGE	1530	1600	30	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT DRY
5/17/2003	4	OPEN RANGE	0630	0715	45	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	HOT DRY
5/17/2003	4	OPEN RANGE	0715	0720	5	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	HOT DRY
5/17/2003	4	OPEN RANGE	0720	0825	65	COLLECTING DATA	RUNNING OPEN RANGE, D2 BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA	GPS	NA	LINEAR	HOT DRY
5/17/2003	4	OPEN RANGE	0825	0921	56	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK COLLECTING DATA		GPS	NA	NA	HOT DRY
5/17/2003	4	OPEN RANGE	0921	1040	79	COLLECTING DATA	RUNNING OPEN RANGE, B5 BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA	GPS	NA	LINEAR	HOT DRY
5/17/2003	4	OPEN RANGE	1040	1045	5	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK BREAK/LUNCH		GPS	NA	NA	HOT DRY
5/17/2003	4	OPEN RANGE	1045	1120	35	COLLECTING DATA	CHOW	NA	NA	NA	HOT DRY
5/17/2003	3	OPEN RANGE	1120	1230	70	COLLECTING DATA	RUNNING OPEN RANGE, B5 BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA	GPS	NA	LINEAR	HOT DRY
5/17/2003	3	OPEN RANGE	1230	1245	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK BREAK/LUNCH		GPS	NA	NA	HOT DRY
5/17/2003	3	OPEN RANGE	1245	1335	50	COLLECTING DATA	BREAK	NA	NA	NA	HOT DRY
5/17/2003	3	OPEN RANGE	1335	1400	25	COLLECTING DATA	CONDUCTED EQUIPMENT INTERFERENCE TEST	GPS	NA	NA	HOT DRY
5/17/2003	3	OPEN RANGE	1400	1430	30	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT DRY

Date	No. of People	Area Tested	Status		Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions	
			Start Time	Stop Time							HOT	DRY
5/19/2003	4	OPEN RANGE	0600	0615	15	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	0615	0620	5	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	0620	0743	83	COLLECTING DATA	RUNNING OPEN RANGE, B4 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/19/2003	4	OPEN RANGE	0743	0815	32	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK COLLECTING DATA	CHECKING/ DOWNLOADING DATA	NA	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	0815	0930	75	COLLECTING DATA	RUNNING OPEN RANGE, B4 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/19/2003	4	OPEN RANGE	0930	0945	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	NA	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	0945	0950	5	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHANGE OUT BATTERY	NA	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	0950	0955	5	BREAK/LUNCH	BREAK	NA	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	0955	1005	10	COLLECTING DATA	RUNNING OPEN RANGE, B4 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/19/2003	4	OPEN RANGE	1005	1010	5	SET UP/MOBILIZATION	SET UP ON GRID C2,C3	NA	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	1010	1024	14	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	1024	1130	66	COLLECTING DATA	RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/19/2003	4	OPEN RANGE	1130	1145	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	1145	1310	85	BREAK/LUNCH	CHOW/BREAK	NA	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	1310	1410	60	COLLECTING DATA	RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions
5/19/2003	4	OPEN RANGE	1410	1420	10	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK SET UP/MOBILIZATION	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	DRY
5/19/2003	4	OPEN RANGE	1420	1430	10	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	DRY
5/20/2003	4	OPEN RANGE	0530	0545	15	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	DRY
5/20/2003	4	OPEN RANGE	0545	0549	4	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	DRY
5/20/2003	4	OPEN RANGE	0549	0718	89	COLLECTING DATA	RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	DRY
5/20/2003	4	OPEN RANGE	0718	0738	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	DRY
5/20/2003	4	OPEN RANGE	0738	0805	27	BREAK/LUNCH	BREAK	NA	NA	NA	DRY
5/20/2003	4	OPEN RANGE	0805	0847	42	COLLECTING DATA	RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	DRY
5/20/2003	4	OPEN RANGE	0847	0900	13	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	DRY
5/20/2003	4	OPEN RANGE	0900	0937	37	COLLECTING DATA	RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	DRY
5/20/2003	4	OPEN RANGE	0937	0952	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	DRY
5/20/2003	4	OPEN RANGE	0952	1012	20	BREAK/LUNCH	BREAK	NA	NA	NA	DRY
5/20/2003	4	YUMA EXTREME	1012	1024	12	SET UP/MOBILIZATION	SET UP IN YUMA EXTREME	NA	NA	NA	DRY
5/20/2003	4	YUMA EXTREME	1024	1111	47	COLLECTING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions
5/20/2003	4	YUMA EXTREME	1111	1130	19	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	DRY
5/20/2003	4	YUMA EXTREME	1130	1230	60	BREAK/LUNCH	LUNCH	NA	NA	NA	DRY
5/20/2003	4	YUMA EXTREME	1230	1245	15	SET UP/MOBILIZATION	SETUP	NA	NA	NA	DRY
5/20/2003	4	YUMA EXTREME	1245	1248	3	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	DRY
5/20/2003	4	YUMA EXTREME	1248	1255	7	COLLECTING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	DRY
5/20/2003	4	YUMA EXTREME	1255	1300	5	DOWNTIME DUE TO EQUIPMENT FAILURE	FIELD COMPUTER OVERHEAT/FAILED	NA	NA	NA	DRY
5/20/2003	4	YUMA EXTREME	1300	1310	10	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	DRY
5/21/2003	3	YUMA EXTREME	0530	0550	20	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	DRY
5/21/2003	3	YUMA EXTREME	0550	0600	10	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	DRY
5/21/2003	3	YUMA EXTREME	0600	0605	5	COLLECTING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	DRY
5/21/2003	3	YUMA EXTREME	0605	0614	9	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	DRY
5/21/2003	3	YUMA EXTREME	0614	0750	96	COLLECTING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	DRY
5/21/2003	3	YUMA EXTREME	0750	0810	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions
5/21/2003	3	YUMA EXTREME	0810	0820	10	BREAK/LUNCH	BREAK	NA	NA	NA	DRY
5/21/2003	3	YUMA EXTREME	0820	0850	30	COLLECTING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	DRY
5/21/2003	3	YUMA EXTREME	0850	0920	30	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLADING DATA	GPS	NA	NA	DRY
5/21/2003	3	MOGUL AREA	0920	0930	10	SET UP/MOBILIZATION	SET UP IN MOGUL AREA	NA	NA	NA	DRY
5/21/2003	3	MOGUL AREA	0930	1040	70	COLLECTING DATA	RUNNING MOGUL AREA, BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	DRY
5/21/2003	3	MOGUL AREA	1040	1100	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLADING DATA	GPS	NA	NA	DRY
5/21/2003	3	MOGUL AREA	1100	1158	58	COLLECTING DATA	RUNNING MOGUL AREA, BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	DRY
5/21/2003	3	MOGUL AREA	1158	1210	12	DOWNTIME DUE TO EQUIPMENT FAILURE	GPS MOUNT BROKE, OPERATOR ERROR	NA	NA	NA	DRY
5/21/2003	3	MOGUL AREA	1210	1230	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLADING DATA	GPS	NA	NA	DRY
5/21/2003	3	MOGUL AREA	1230	1237	7	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	DRY
5/21/2003	3	MOGUL AREA	1237	1322	45	COLLECTING DATA	RUNNING MOGUL AREA, BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	DRY
5/21/2003	3	MOGUL AREA	1322	1335	13	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLADING DATA	GPS	NA	NA	DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions
5/21/2003	3	MOGUL AREA	1335	1445	70	COLLECTING DATA	RUNNING MOGUL AREA, BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	HOT DRY
5/21/2003	3	MOGUL AREA	1445	1500	15	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT DRY
5/22/2003	3	YUMA EXTREME	0530	0637	67	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	HOT DRY
5/22/2003	3	YUMA EXTREME	0637	0642	5	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	HOT DRY
5/22/2003	3	YUMA EXTREME	0642	0745	63	COLLECTING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	HOT DRY
5/22/2003	3	YUMA EXTREME	0745	0800	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT DRY
5/22/2003	3	YUMA EXTREME	0800	0930	90	COLLECTING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	HOT DRY
5/22/2003	3	YUMA EXTREME	0930	0935	5	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	SWAP OUT BATTERIES	NA	NA	NA	HOT DRY
5/22/2003	3	YUMA EXTREME	0935	0950	15	COLLECTING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	HOT DRY
5/22/2003	3	YUMA EXTREME	0950	1005	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT DRY
5/22/2003	3	YUMA EXTREME	1005	1020	15	BREAK/LUNCH	BREAK	NA	NA	NA	HOT DRY
5/22/2003	3	CALIBRATION PIT	1020	1028	8	SET UP/MOBILIZATION	SET UP OVER CALIBRATION PIT	NA	NA	NA	HOT DRY
5/22/2003	3	CALIBRATION PIT	1028	1030	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	HOT DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions	
											HOT	DRY
5/22/2003	3	CALIBRATION PIT	1030	1052	22	COLLECTING DATA	RUNNING SIGNATURE DATA ON 40MM MARK II	GPS	NA	LINEAR		
5/22/2003	3	CALIBRATION PIT	1052	1105	13	COLLECTING DATA	RUNNING SIGNATURE DATA ON 57MM	GPS	NA	LINEAR	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1105	1128	23	COLLECTING DATA	RUNNING SIGNATURE DATA ON 60MM	GPS	NA	LINEAR	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1128	1138	10	BREAK/LUNCH	BREAK	NA	NA	NA	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1138	1149	11	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1149	1240	51	BREAK/LUNCH	LUNCH	NA	NA	NA	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1240	1243	3	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1243	1255	12	COLLECTING DATA	RUNNING SIGNATURE DATA ON ROCKEYE MK118	GPS	NA	LINEAR	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1255	1320	25	COLLECTING DATA	RUNNING SIGNATURE DATA ON 2.75 ROCKET	GPS	NA	LINEAR	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1320	1347	27	COLLECTING DATA	RUNNING SIGNATURE DATA ON 105 STANDARD	GPS	NA	LINEAR	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1347	1412	25	COLLECTING DATA	RUNNING SIGNATURE DATA ON 155MM	GPS	NA	LINEAR	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1412	1414	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1414	1500	46	DEMOBILIZATION	END OF TEST	NA	NA	NA	HOT	DRY

## **APPENDIX E. REFERENCES**

1. Standardized UXO Technology Demonstration Site Handbook, DTC Project No. 8-CO-160-000-473, Report No. ATC-8349, March 2002.
2. Aberdeen Proving Ground Soil Survey Report, October 1998.
3. Data Summary, UXO Standardized Test Site: APG Soils Description, May 2002.
4. Yuma Proving Ground Soil Survey Report, May 2003.
5. Practical Nonparametric Statistics, W.J. Conover, John Wiley & Sons, 1980, ages 144 through 151.



## **APPENDIX F. ABBREVIATIONS**

AEC	=	U.S. Army Environmental Center
APG	=	Aberdeen Proving Ground
ATC	=	U.S. Army Aberdeen Test Center
EMI	=	electromagnetic interference
EMIS	=	Electromagnetic Induction Spectroscopy
ERDC	=	U.S. Army Corps of Engineers Engineering Research and Development Center
ESTCP	=	Environmental Security Technology Certification Program
EQT	=	Army Environmental Quality Technology Program
GPS	=	Global Positioning System
JPG	=	Jefferson Proving Ground
PDA	=	personal digital assistant
POC	=	point of contact
PVC	=	polyvinyl chloride
QA	=	quality assurance
QC	=	quality control
ROC	=	receiver-operating characteristic
RTK	=	real time kinematic
SERDP	=	Strategic Environmental Research and Development Program
UXO	=	unexploded ordnance
YPG	=	U.S. Army Yuma Proving Ground

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